Image: D. Schlege

Probing primore an one caussenity <u>ov reconstructing the inter</u> conditions with magnine learning

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Planck, ACT, Simons Observatory, CMB-S4, ...



DESI, *Euclid*, *Roman, ...*



Image: Nicolle R. Fuller, National Science Foundation

Understand the mechanism behind inflation

- Inflation seeded the density fluctuations that we can observe today
- Primordial non-Gaussianities (PNG): deviations from the initial Gaussian density fluctuations. Consequence of many inflation models, robust probe of dynamics during inflation
- • $f_{\rm NL}$: local, equilateral, orthogonal

Local type $f_{\rm NI}^{\rm loc}$

 $\Phi(\mathbf{x}) = \phi(\mathbf{x}) + f_{\rm NL}^{\rm loc} \{ \phi^2(\mathbf{x}) - \langle \phi^2(\mathbf{x}) \rangle \} + \dots$ Primordial potential Gaussian field

 Sensitive probe of multi-field models • Multi-field: $|f_{\rm NL}^{\rm loc}| > 1$, single field $|f_{\rm NL}^{\rm loc}| < 0.01$

A sensitivity of $|f_{\rm NL}^{\rm loc}| < 1: \sigma(f_{\rm NL}^{\rm loc}) < 1$



Status of CMB



- Current best: 0.9±5.1 (Planck Collaboration 2020)
- Limited by **2D** nature
- •Only a factor of 2 improvement in future
- •CMB secondary probes x LSS

Status of LSS



- •Current best: -12±21 (eBOSS DR16 QSO, Mueller et al. 2022)
- Many more modes from 3D
- Scale-dependent bias of galaxy power spectrum
 - Systematics
 - •Cosmic variance on large scales
- Forecast DESI $\sigma(f_{\rm NI}) \sim 10$ (Sailer et al. 2021)
- Adding Bispectrum -> tighter constraints
 - •A factor of ~3 Pk -> Bk, ~4 Pk -> Pk+Bk (e.g., Dore et al. 2014)
 - Large data vectors
 - Large bispectrum from gravity



• Field level fits

Reconstruction





New approach to constrain PNG

- Reconstructing the density field
- Fitting templates at field level
- Computing and fitting a near-optimal bispectrum estimator

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Reconstruction of the initial conditions: reverse a late-time density field back to initial density field

Acoustic feature



Lagrangian displacement field

Padmanabhan et al. 2012



Present day



Idea behind standard reconstruction (Eisenstein et al. 2007)

•The initial density field in the early universe is very smooth

•As the universe evolves, the black points spread out which broadens the acoustic feature

•Estimate the displacement field and move the particles back to their initial positions.

•Reduces the distance error in BAO analysis by a factor of ~2

Density field reconstructed by the standard reconstruction algorithm still nonlinear





Late-time

Standard reconstruction

Matter density fields at high resolution (1024³ particles in 1 Gpc/h box) at z=0, on a 512³ grid, using Quijote simulations (Villaescusa-Navarro et al. 2020)



Initial





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Initial





A new reconstruction method

based on perturbation theory



A hybrid method that combines convolutional neural network (CNN) with traditional algorithm





Density field by CNN trained with late-time density field

Extract information from this volume to determine the reconstructed density at the center



Late-time

- Considers neighbor points by grouping them in a batch
- Trains with 8 simulations, normalized field, with initial density field the target



Initial

CNN trained w/ late-time field



Training with *reconstructed* density field significantly improves performance

CNN is relatively local. Algorithm provides good approximation on large scale (Zel'dovich approximation is only valid for large scales). CNN then reconstructs further on smaller scales.



Late-time

Standard recon

CNN trained w/ standard recon field

14

Initial

CNN improves cross-correlation

Real space

$$r(k) = \frac{\langle \delta^*(k) \delta_{\text{ini}}(k) \rangle}{\sqrt{\langle \delta^2(k) \rangle \langle \delta_{\text{ini}}^2(k) \rangle}}$$

- CNN+Algorithm performs significantly better than algorithms alone and CNN+Late-time density field
- •CNN+ES3 and CNN+HE18 are similar

Two reconstruction algorithms:

- Eisenstein et al. 2007, **ES3**, i.e., standard
- Hada & Eisenstein 2018, **HE18**

Now adding PNG...

Three categories of sims: $f_{\rm NL} = 0, f_{\rm NL} = +100, f_{\rm NL} = -100$

Model trained with no PNG works for PNG $G(k) = \frac{\langle \delta^*(k) \delta_{\text{ini}}(k) \rangle}{\langle \delta^2_{\text{ini}}(k) \rangle}$

CNN+HE18

New approach to constrain PNG

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Templates for fitting $f_{\rm NI}$

- • δ_G =No PNG IC
- $\bullet \delta_{f_{\rm NL}} = \phi_G^2(k) M_{\phi}(k)$
- • $\delta^2, \delta_{\nabla^2}, \delta_{S^2}$ all computed using δ_G

Small error but fits are slightly biased

Chen, Padmanabhan & Eisenstein in prep.

Accounting for the shift in the mean at $f_{\rm NL} = 0$:

$$f_{\rm NL} = 100$$
:

For >2 Gpc survey volume (e.g. DESI): $\sigma(f_{\rm NI}) \sim 2$

- Errors in 1 Gpc volume, std of 90 sims
- •With 5 Mpc/h smoothing for the quadratic fields
- •k cut at 0.1 h/Mpc

| | b_2 | $ b_{ abla^2}$ | b_{s^2} | | |
|---|-------------|-----------------|-------------|--|--|
| | 0.006±0.001 | -0.014±0.001 | 0.014±0.001 | | |
| | 0.005±0.001 | -0.015±0.001 | 0.014±0.001 | | |
| 6 | 0.007±0.001 | -0.014±0.001 | 0.013±0.001 | | |
| | | | | | |

- ~92
- 100: ~-92

Small error but fits are slightly biased

Chen, Padmanabhan & Eisenstein in prep.

From F₂ kernel:

- Errors in 1 Gpc volume, std of 90 sims
- •With 5 Mpc/h smoothing for the quadratic fields
- •k cut at 0.1 h/Mpc

| | b_2 | $b_{ abla^2}$ | b_{s^2} |
|---|-------------------|---------------|-------------|
| 7 | 0.006 ± 0.001 | -0.014±0.001 | 0.014±0.001 |
| | 0.005 ± 0.001 | -0.015±0.001 | 0.014±0.001 |
| 6 | 0.007±0.001 | -0.014±0.001 | 0.013±0.001 |

| near | b_2 | $b_{ abla^2}$ | b_{s^2} |
|-------|-------------------|---------------|-------------|
| = 0 | 0.825±0.006 | -1.018±0.008 | 0.188±0.005 |
| +100 | 0.825 ± 0.007 | -1.018±0.010 | 0.188±0.005 |
| - 100 | 0.825±0.006 | -1.018±0.007 | 0.188±0.005 |

$$b_2 = \frac{17}{21} \sim 0.81 \quad b_{\nabla^2} = -1 \quad b_{s^2} = \frac{4}{21} \sim 0.1$$

Strong degeneracy between $f_{\rm NL} {\rm and} \ b_2$

Cross-correlation coefficient between

$$f_{\rm NL} - b_2$$
: ~-0.6
 $f_{\rm NL} - b_{\nabla^2}$: ~-0.2
 $f_{\rm NL} - b_{s^2}$: ~0.4

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Near optimal bispectrum estimator **Reconstructed/Linear** Primordial potential $\Phi(k) = \frac{\delta(k)}{M_{\Phi}(k)}$ $M_{\Phi}(k) = \frac{2}{3} \frac{k^2 T(k)}{Q_{\Phi}(k)^2}$ $\Phi^{2}(k) = \left[dx e^{-ik \cdot x} \Phi^{2}(x) = \frac{1}{(2\pi)^{3}} \right] \left[dk_{1} \Phi(k_{1}) \Phi(k - k_{1}) \right]$ $\left\langle \Phi^2(\mathbf{k})\delta(-\mathbf{k})\right\rangle = \frac{1}{(2\pi)^3} \int \mathrm{d}\mathbf{k}_1 M_{\Phi}(-\mathbf{k}) \left\langle \Phi(\mathbf{k})\Phi(\mathbf{k}-\mathbf{k}_1)\Phi(-\mathbf{k})\right\rangle$ **Primordial bispectrum**

Why near optimal? Maximum likelihood estimation by Schmittfull, Baldauf & Seljak 2015

Near optimal bispectrum estimator as a statistic

with cosine filter between k=0.2-0.25 h/Mpc

- Biased, consistent with template fits
- Trying to understand and minimize the bias
- •Forecast with a model based on perturbation theory at tree level w/o b_2 gives $\sigma(f_{\rm NL})$ ~1.5. Need to fit together due to high degeneracy. Error will be larger.

V0.1 GCcomb postrecon errors of the **BAO** parameters

Summary

- Reconstruction with CNN+algorithm shows promising constraining power for PNG • Template fits are biased but errors are lower Bispectrum estimator consistent with template fitting

- Minimizing the bias ongoing
- Plan:
 - Fitting templates in reality: fitting coefficients together with δ_G , forward model • Estimate each template term with bispectrum estimator

 - High shot noise biased tracer

Thank you!