Galaxy Cluster Mass Estimation Using Deep Learning

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MACS J0416.1-2403 Image Credit: Hubble

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Collaborators



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Introduction: Dynamical Probes of Dark Matter

Astronomy in the 1930s



1925 - Cecilia Payne-Gaposchkin discovers the abundance of hydrogen in stellar spectra.

1929 - Edwin Hubble publishes studies on the distance-redshift relation.

A SPIRAL NEBULA AS A STELLAR SYSTEM, MESSIER 31¹

By EDWIN HUBBLE

1924 - Edwin Hubble observes proof that `faint nebulae' were, in fact, other galaxies.





1932 - Karl Jansky builds the first radio telescope

Fritz Zwicky and the Coma Cluster



Scheinbare Geschwindigkeiten im Comahaufen.

v=8500 km/sek	6900 km/sek
7900	6700
7600	6600
7000	5100 (?)



Fritz Zwicky and the Coma Cluster

tungen an leuchtender Materie abg vahrheiten sollte, würde sich also das ben, dass dunkle Materie in sehr viel t als leuchtende Materie.

Zwicky's observation and analysis of the Coma cluster mass is often considered to be the first inference of dark matter!*[†]



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* Kelvin (1884), Kapteyn (1922), Oort (1932) † Not widely accepted until Rubin, Ford, and Freeman in the 1970s



90 Years Later...

What is Dark Matter?

Millennium Simulations

The Halo Mass Function (HMF)



MultiDark Resimulations (Kristin Riebe)

Halo mass



"Most massive bound structures in the universe"



MACS J0416.1-2403 Image Credit: Hubble





To constrain the HMF:

- Large, well-defined cluster sample
- Robust mass-measurement methods
 - Efficient and automated

Mass Measurements of Galaxy Clusters



Dynamical Masses and The M- σ

Assuming: spherical symmetry, gravitational equilibrium, identical galaxies, perfect selection



$$\sigma_v \propto [M_{200c}]^{\alpha}$$
$$\alpha \approx 1/3$$





First-order stats are not sufficient to capture galaxy dynamics!

Previous work has investigated impacts of:

- Dynamical substructure (Old et al. 2018)
- Halo environment (White et al. 2010)
- Triaxiality (Svensmark et al. 2015)
- Mergers (Evrard et al. 2008)
- Sample Contamination (Wojtak et al. 2018)





Dynamical Masses from Deep Learning

Dynamical Masses from Deep Learning (Ho et al. 2019)

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Our model should...

- Learn to identify features representative of cluster substructure and interlopers
- Relate these features to mass predictions in a complex manner



A Very Brief Guide to Deep Neural Networks

Deep Neural Networks

- Highly non-linear functions with nice gradients
- Very overparameterized (100,000+ parameters)



A Very Brief Guide to Convolutional Neural Networks

Convolutional Neural Networks (CNNs)

- Gold standard for image-recognition tasks
- Utilize shared feature filters in first layers
- Find localized patterns in subinputs



A Very Brief Guide to Convolutional Neural Networks

• Training feature filters:



Convolutional Networks for Cluster Mass Estimation²¹



Dynamical Masses from Deep Learning (Ho et al. 2019)



Low bias and Gaussian scatter

- Models reduce scatter of simple M-σ measurements by <u>a factor of ~2.5</u>.
- Models improve prediction scatter relative to 'ideal' Mσ measurements (i.e. no selection effects) by 30%.



Interpreting Dynamical Deep Learning

Deep learning models learn to downvote interlopers and emphasize substructure.



Doogesh Kodi Ramanah (DARK)

arXiv:2003.05951 arXiv:2009.03340



Dynamical Masses from Deep Learning (Ho et al. 2019)

Robustness

- Reduced sensitivity to cluster richness
- **Computational Efficiency**
- Reduced training+inference time by 30x when compared to other ML approaches (SDM; Ntampaka et al. 2015, 2016)



Uncertainty on Deep Learning Mass Estimates

Uncertainty in Deep Learning

Methods to recover deep learning uncertainties:

- Approximate Bayesian Neural Networks (Ho et al. 2020)
- Forward modeling
- Normalizing Flows (Ramanah et al. 2020)
- Simulation-based inference (Ramanah et al. 2020)



 $\Rightarrow p(M_{200c}|\mathbf{x})$

<u>Aleatoric uncertainty</u> - Intrinsic scatter in input-output relationships

$$p(m \mid \mathbf{x}, \theta, \eta)$$

We can choose this distribution can be:

- Normal or log-normal
- Categorical
- Poisson
- Etc.



$$f(\mathbf{x}; \theta) \to \mathcal{N}(\mu, \sigma)$$

<u>Epistemic uncertainty</u> - Uncertainty in parameter settings achieved during model training

 $p(\theta \mid \eta, \mathcal{D})$

Sources of epistemic uncertainty:

- Insufficient training data
- Limited training time
- Inflexible model architectures





$$\underbrace{p(\mathbf{m} \mid \mathbf{x}, \boldsymbol{\eta}, \mathcal{D})}_{\text{Mass posterior}} = \int \underbrace{p(\mathbf{m} \mid \mathbf{x}, \boldsymbol{\theta}, \boldsymbol{\eta}) p(\boldsymbol{\theta} \mid \boldsymbol{\eta}, \mathcal{D}) d\boldsymbol{\theta}}_{\text{Output of NN}} \underbrace{p(\mathbf{m} \mid \mathbf{x}, \boldsymbol{\theta}, \boldsymbol{\eta}) p(\boldsymbol{\theta} \mid \boldsymbol{\eta}, \mathcal{D}) d\boldsymbol{\theta}}_{\text{weights}}$$

Intractable for deep neural networks!

$$\begin{split} \mathbf{m} &:= \text{Cluster mass} \\ \mathbf{x} &:= \text{Input observables} \\ \boldsymbol{\eta} &:= \text{Model architecture} \\ \mathcal{D} &:= \text{Training data} \end{split}$$

 $\boldsymbol{\theta} := \text{Model weights}$

 $\theta \sim \theta_0 \cdot \text{Bernoulli}(p)$

Dropout Variational Inference (Gal & Ghahramani 2016)

- Randomly set some fraction *p* of weights to 0 during both training and inference
- Evaluate many random realizations, then average their outputs



Output



Approximate Bayesian Uncertainties on Deep Learning Mass Estimates (Ho et al. 2020)



$$p(m \mid \mathbf{x}, \theta, \eta) \longrightarrow$$
 Normal, Categorical
 $p(\theta \mid \eta, \mathcal{D}) \longrightarrow \theta \sim \theta_0 \cdot \text{Bernoulli}(p)$

Same catalog and train/test procedures as original paper

Approximate Bayesian Uncertainties on Deep Learning Mass Estimates (Ho et al. 2020)

 Model posteriors are Gaussian, even when given high flexibility. They are consistent with true cluster masses, with low predictive scatter and bias for median predictions.



Approximate Bayesian Uncertainties on Deep Learning Mass Estimates (Ho et al. 2020)

- Model posteriors are well calibrated for mid-range mass clusters. The best performing models can recover within +/-1% of 64 and 90 percentile confidence intervals.
- Slight biases exist for very high/low mass clusters at the edges of our training set
- Epistemic uncertainties don't necessarily improve our posterior calibration



Empirical Verification

Application to Observation - Coma Cluster

Validate our model prediction on well-studied systems ~100 galaxy spectra from SDSS above $M_{\rm stellar} \ge 10^{10.5} h^{-1} M_{\odot}$



Coma Cluster, Schulman Telescope

Multiwavelength Probes of Dark Matter

Multiwavelength Measurements



Multiwavelength Feature Analysis

Combining mass proxies using machine learning tools (LR, RFs, DTs, k-NN):

Feature set	Included Features
PHOT:	$R_{\text{mean, std, skew, kurt}}, m_{\text{mean, std, skew, kurt}}, N_{\text{gal}}, e$
SPEC:	PHOT + $v_{\text{mean, std, skew, kurt}}$
X:	$T_{500c}, L_{X,500c}$
SZ:	$Y_{\text{SZ,5r}_{500c}}$

 M_{FOF} scatter of ~0.039 dex (Cohn). M_{200c} scatter of ~0.03 dex (Armitage)



Joanne Cohn (LBNL) arXiv:1905.09920

Thomas J. Armitage (Manchester) arXiv:1810.08430

Multi-Wavelength Cluster Measurements

Multi-wavelength observations



Cluster mass distribution



Multi-Wavelength Cluster Measurements



Deep Learning requires **Big Data**

- We are entering an era of large, high-resolution simulations
- Fast, large-volume hydrosims
 - HYPER (He et al. 2021)
- Advanced baryon pasting methods
 - Generative modeling
 - Subgrid pasting

Conclusion

- We introduced an image-recognition based model for calculating cluster masses from galaxy dynamics (Ho et al. 2019).
- Discussed methods for measuring uncertainties from deep learning (Ho et al. 2020).
- Described current applications on real systems such as the Coma, CLASH, and HeCS clusters.
- Detailed attempts toward fully-informed multiwavelength mass estimators.

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