

Detecting galaxy clusters in the DLS and CARS: a Bayesian Cluster Finder

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- Ami Choi (UC Davis)
- James Jee (UC Davis)
- ... and the rest of the DLS team

OUTLINE

- Introduction: Galaxy cluster detection
- The Bayesian Cluster Finder
 - The method
 - Simulations
- Applications
 - DLS
 - CARS
- Work in progress

GALAXY CLUSTER DETECTION

- **GEOMETRY:** Voronoi Tessellation (*Kim et al. 2002, Ramella et al. 2001, Lopes et al. 2004*), Counts in cells (*Couch et al. 1991, Lidman & Peterson 1996*), Percolation FoF Algorithm (*Dalton et al. 1997*).
- **MATCHED FILTER:** (*Postman et al. 1996, 2002*), Adaptive Kernel (*Gal et al. 2000, 2003, 2006*), Hybrid Matched Filter (*Kepner et al. 1999*), Adaptive Matched Filter (*Kim et al. 2002*). High z: Spitzer (*Eisenhardt et al. 2008*)
- **RED SEQUENCE:** MaxBCG (*Hansen et al. 2005, Koester et al. 2007*), The Cluster Red Sequence Method (*Gladders & Yee 2000, López-Cruz et al. 2004, Gladders et al. 2005*), Cut-and-enhance (*Goto et al. 2002*), the C4 clustering algorithm (*Miller et al. 2005*). High z: SpARCS (*Wilson et al. 2008*)

THE BAYESIAN CLUSTER FINDER

- Motivation: to take advantage of all the characteristics of every algorithm.
- Each galaxy in the survey is assigned a Bayesian probability that the galaxy belongs to a cluster at a certain redshift.
- Likelihood: Based on a variation of the Matched Filter Algorithm including photo-z information.
- Introduction of a Bayesian prior: CMR – z relation and BCG magnitude –z relation.

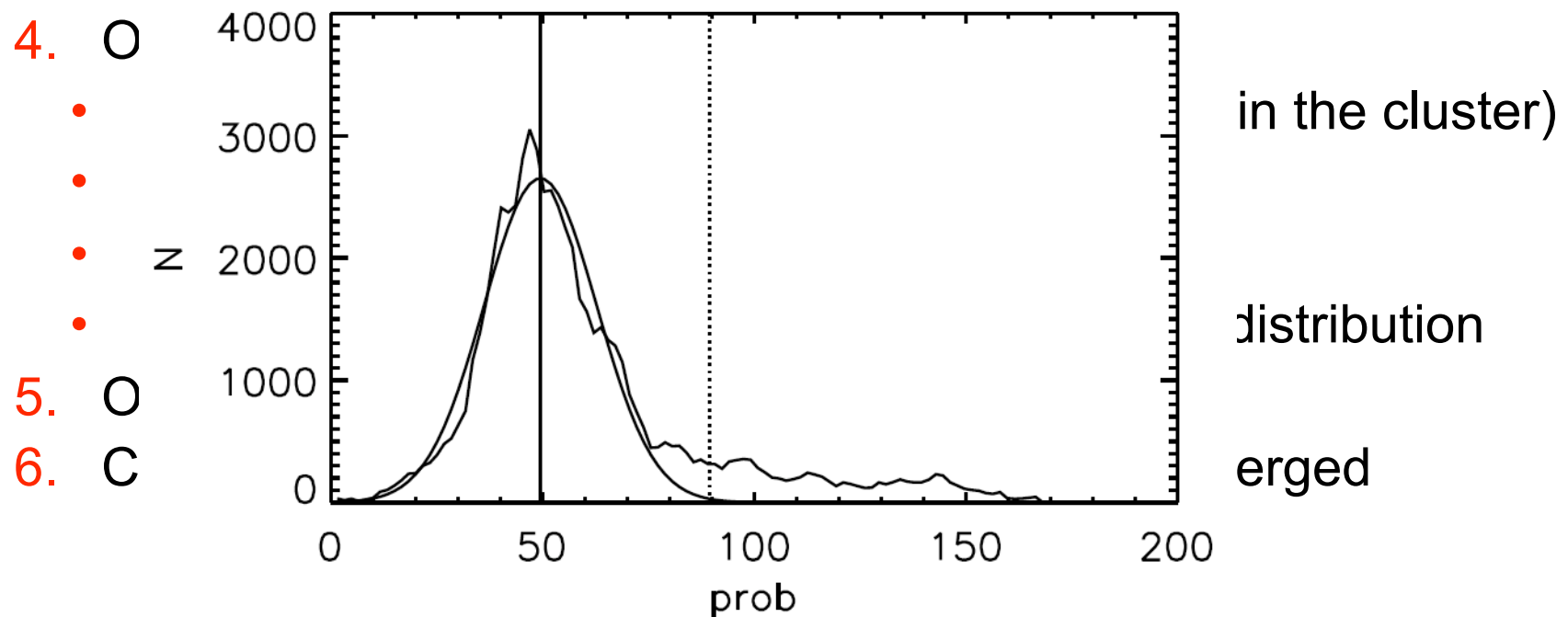
Ascaso et al. 2010b,c, ApJ to be submitted

GALAXY CLUSTERS DETECTION

1. Redshift slices (z_s) from $0.1 \leq z_s \leq 1.2$ in steps of 0.1
2. Each galaxy ($\alpha_i, \delta_i, z_{s,i}$) \rightarrow prob
3. Each z_s \rightarrow background and σ probability. Only select 3σ detections.
4. Output:
 - Richness (Λ_{cl} ; effective number of L^* galaxies in the cluster)
 - Position (α_c, δ_c)
 - Maximum probability redshift z_s
 - Mean redshift (z_m) from the photo-z's galaxy distribution
5. Only keep candidates that $|z_s - z_m| < 0.06(1 + z_s)$
6. Clusters with $D < 1.5 \text{ Mpc}$ and $|z_{s,1} - z_{s,2}| < 0.3$ are merged

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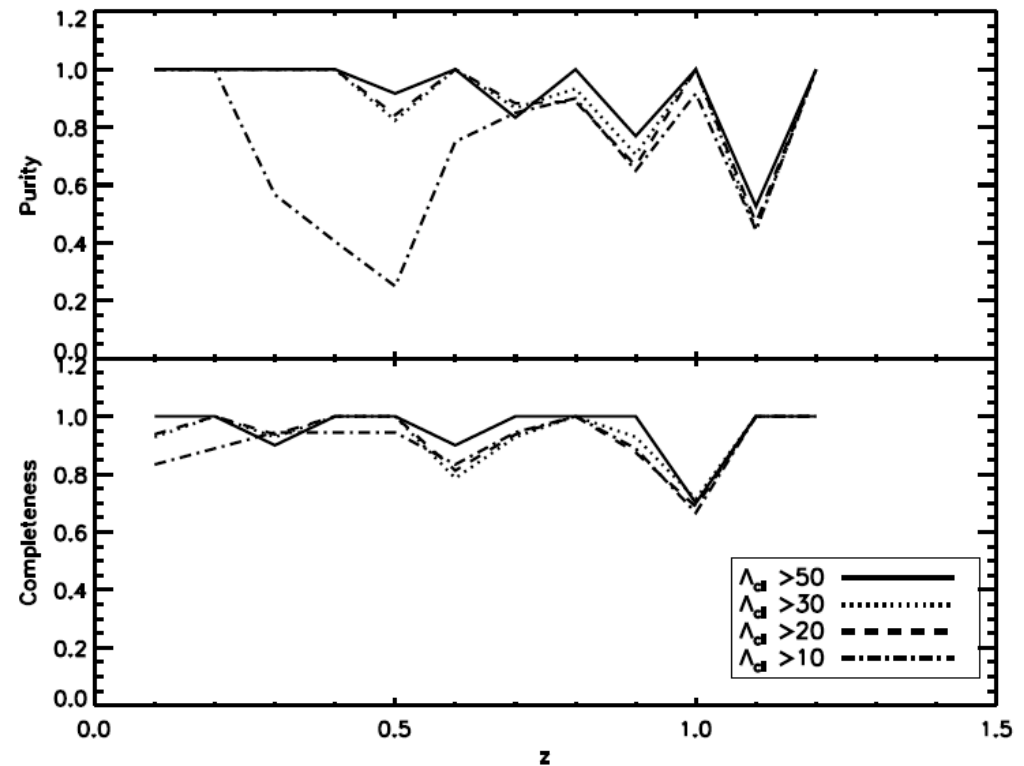
SIMULATIONS

- Clusters
 - Richness: $10 \leq \Lambda_{cl} \leq 250$ (equivalent to $0 \leq RA \leq 4$)
 - Redshifts: $0.1 \leq z_c \leq 1.2$
 - Magnitudes: Schechter LF model with $\alpha = -1.1$ and $M^* = -21$.
 - Positions: Plummer profile.
 - Galaxies redshift: spread as a normal function with $\mu = z_c$ and $\sigma = 2(1+z_c)0.06$
 - Colors: Using spectra templates combined with a spread technique in order to match the observed CMR
- Field galaxies
 - Magnitudes, colors and photo-z distribution from the original data
 - Positions: Rayleigh-Levy two point correlation function

RECOVERY RATE

$$Purity = \frac{\#\{detected\ clusters || simulated\}}{\#\{detected\ clusters\}}$$

$$Completeness = \frac{\#\{simulated\ clusters || detected\}}{\#\{simulated\ clusters\}}$$

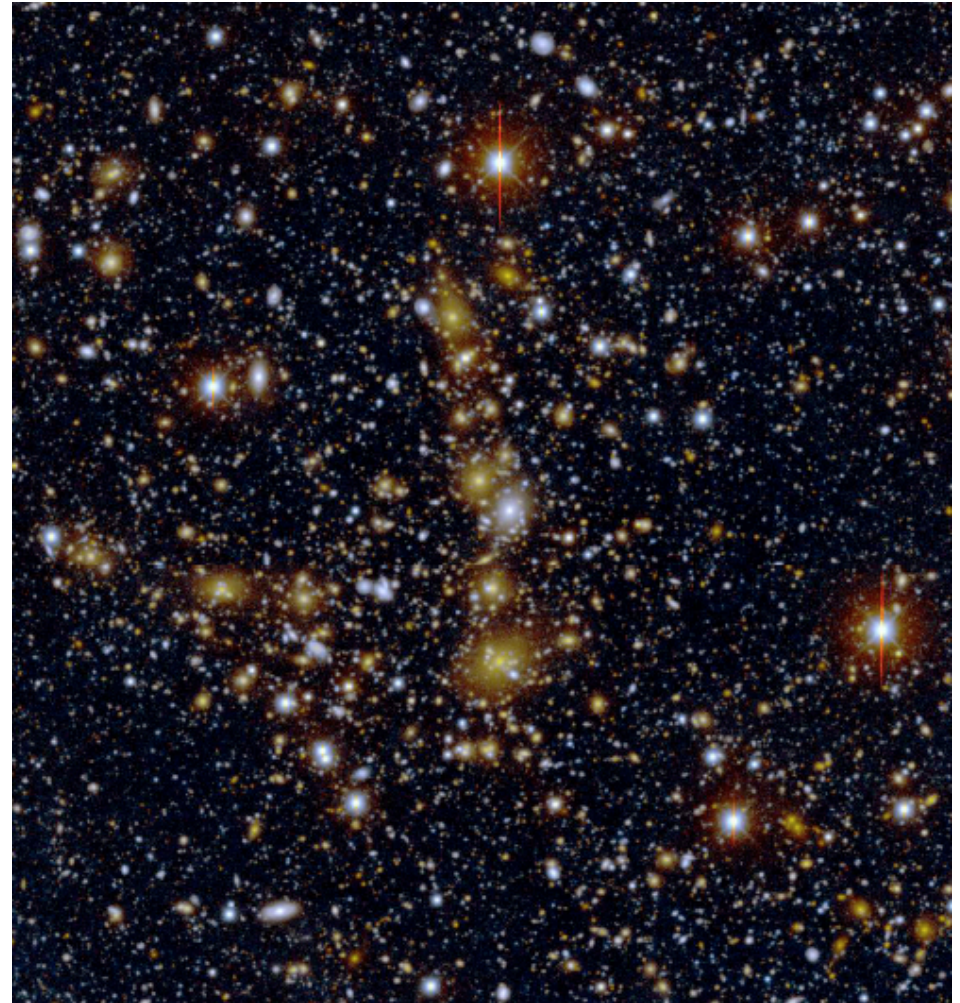


Both purity and completeness rates are over 80%
for clusters richer than $\Lambda_{cl} > 20$ and $z < 1.1$

APPLICATION TO SURVEYS I: DLS

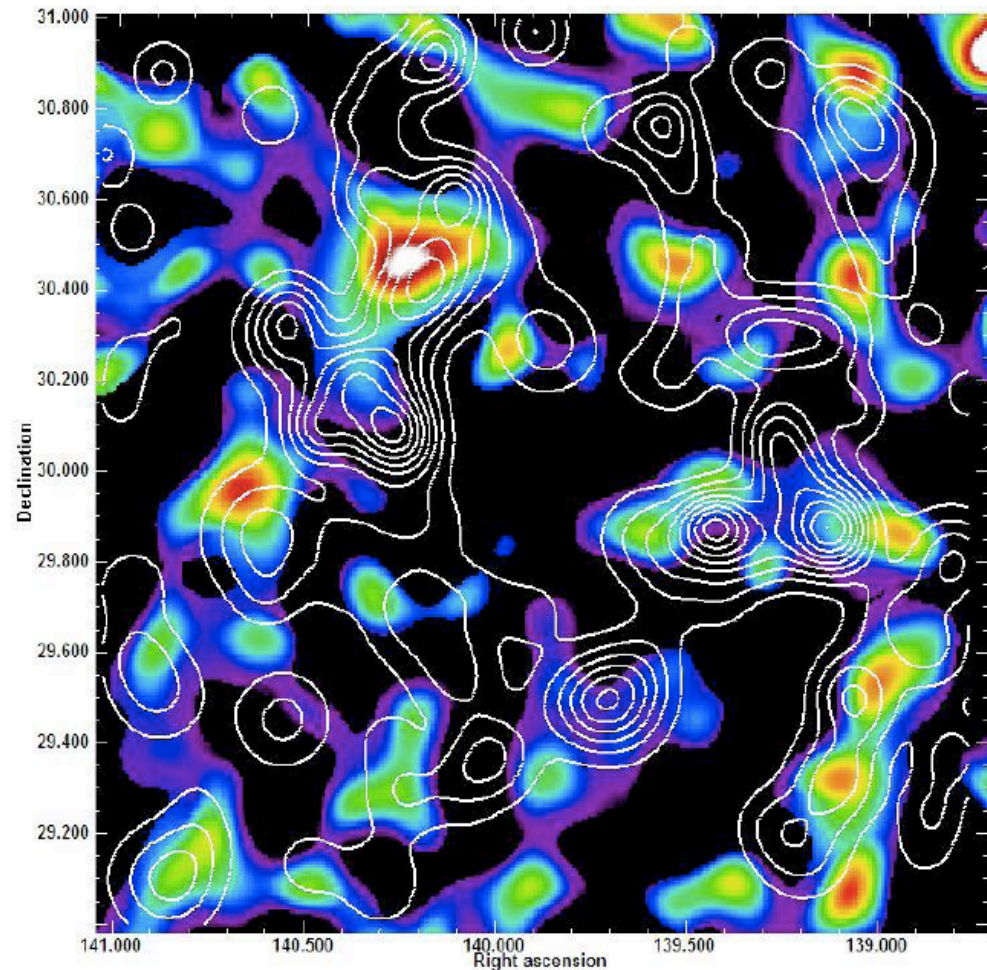
- The Deep Lens Survey (DLS)
 - *Wittman et al. 2002, 2006*
 - $20 \text{ } \square^2$ ($5 \times 4 \text{ } \square^2$).
 - Four optical bands: BVRz, complete up to 26/26/27/26 mag/ \square^2
 - Pixel size: $0.257''$
 - Best seeing in R band ($<0.9''$). For non-R images, seeing averages $\sim 1.2''$

(*Ascaso et al. 2010c, ApJ, to be submitted*)



APPLICATION TO SURVEYS I: DLS

- More than 700 galaxy clusters detected up to $z < 1.2$
- Detect 100% of the optical detections by MaxBCG and the spectroscopically confirmed clusters by *Wittman et al. 2006*
- Large Scale Structure
- Weak Lensing maps (*Dawson et al. 2010 in prep*) correlations with optical detections



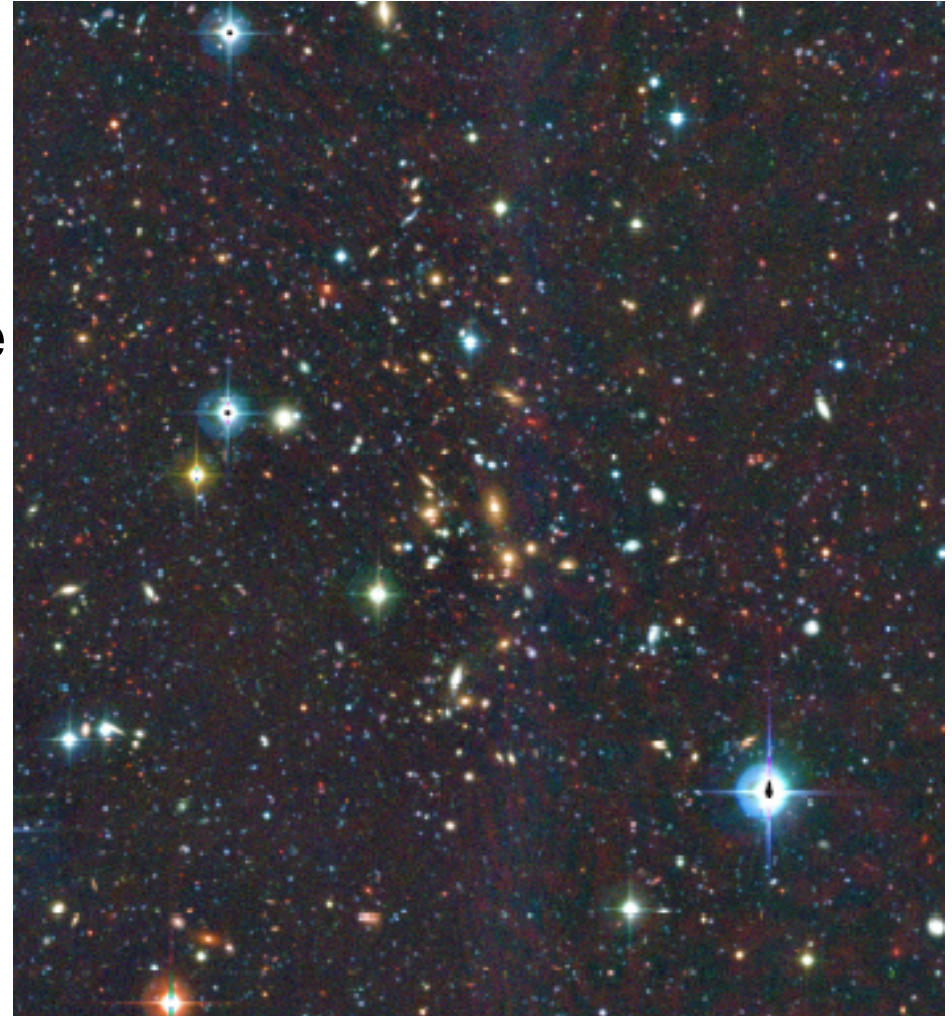
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APPLICATION TO SURVEYS II: CARS

- The CFHTLS-Archive-Research Survey (CARS; *Erben et al. 2009*)
 - based on the public archive images from the CFHTLS-Wide ($37 \text{ } \square^2$)
 - Five optical bands (ugriz)
 - Complete up to 24 in R band
 - Pixel size: $0.186''$
 - BPZ photo-zs (*Benítez 2000*)

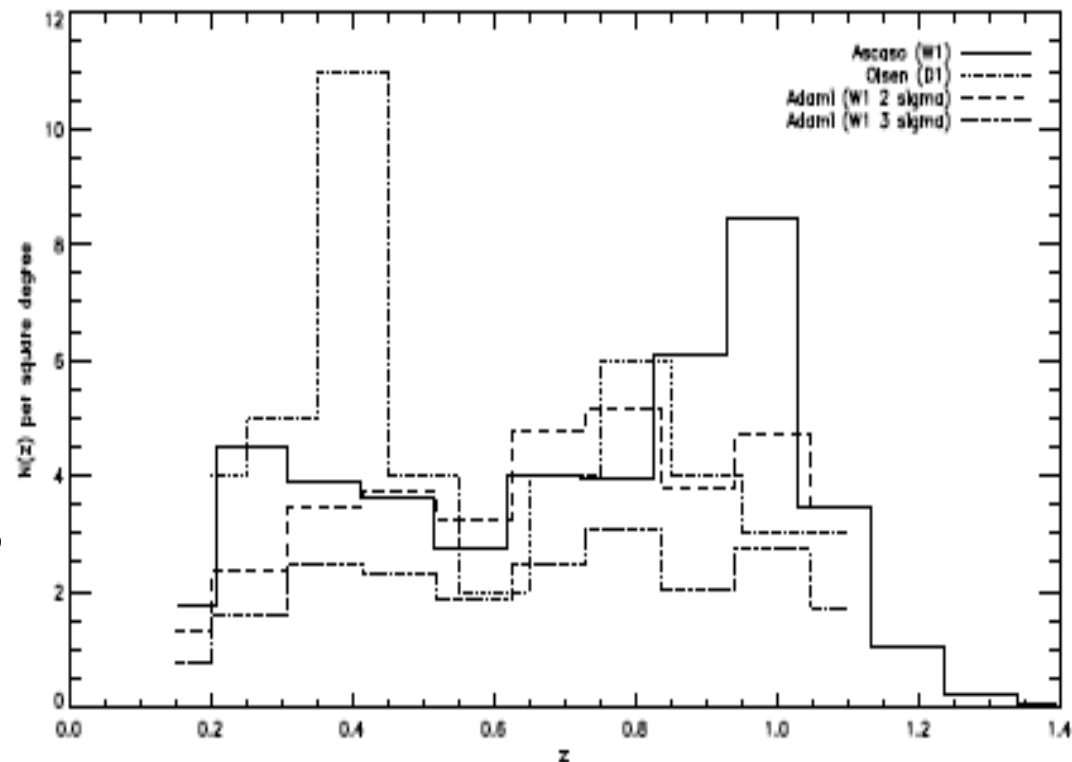
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APPLICATION TO SURVEYS II: CARS

- *Olsen et al. (2007)*:
65% agreement. Many more at high z .

- *Adami et al (2010)*:
We find an agreement of 81% and 74% over 3 and 2σ respectively



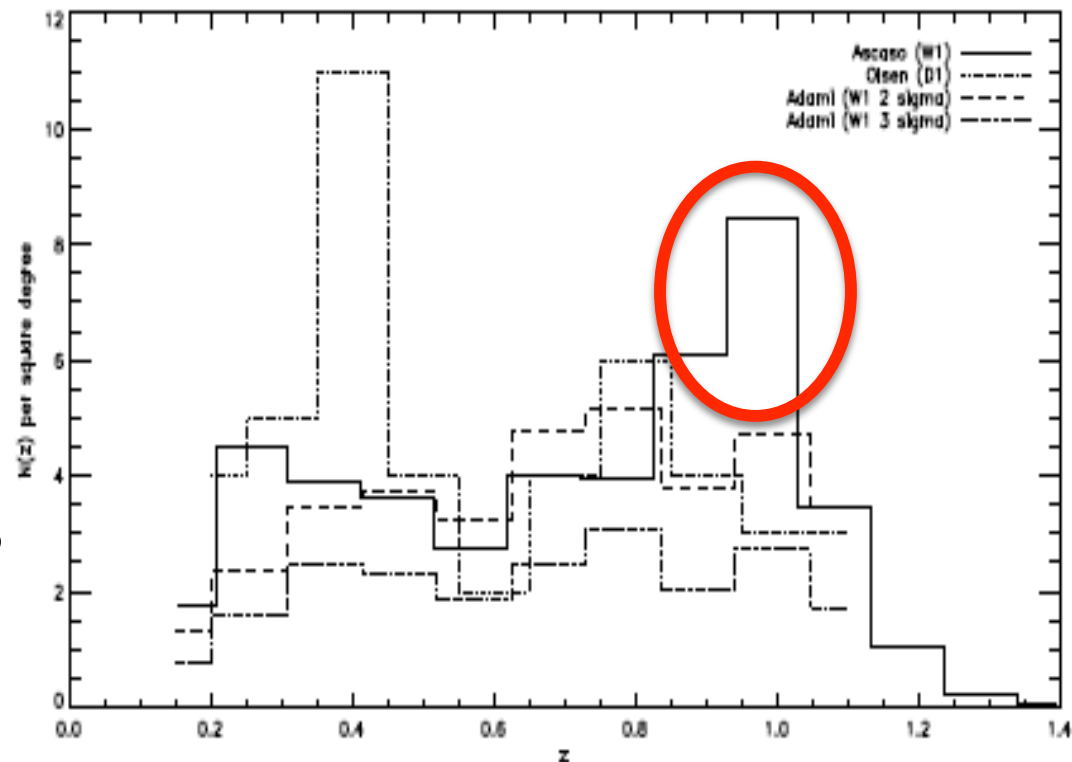
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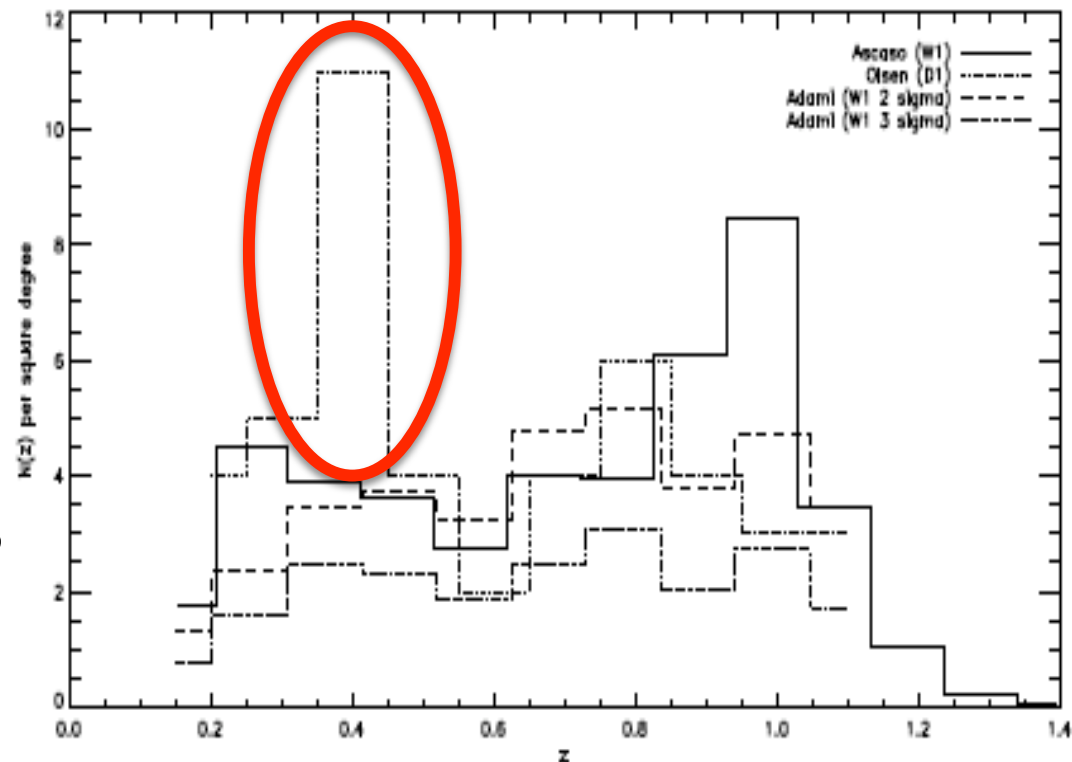
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WORK IN PROGRESS

- Extend the DLS detections to high redshift clusters ($z > 1$) by using existing IR data.
- Developing telescope proposals to confirm the completeness and purity rates and to diminish the photometrical redshift errors.

Comments, suggestions or collaborations
are welcome

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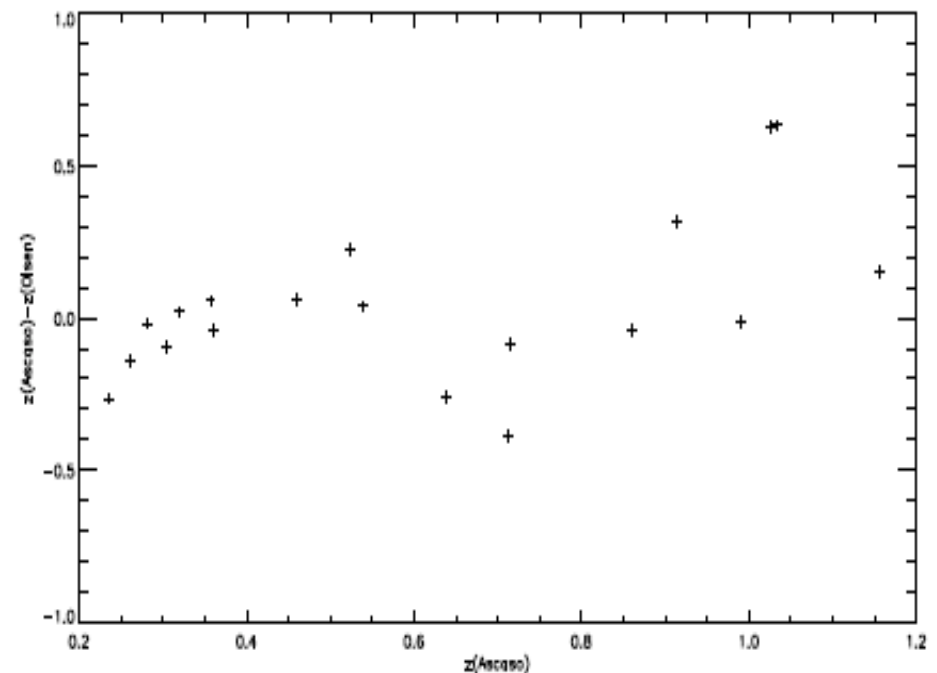
¡GRACIAS!

APPLICATION TO SURVEYS II: CARS

Detections and comparison with other works:

Olsen et al. 2007

- They detect 32 clusters in Deep 1 (one degree overlap with W1) excluding 14 C or D systems.
- We find 62 clusters in W1 (65% in common)
- We detect many more, in particular at $z > 0.9$ in less deep fields



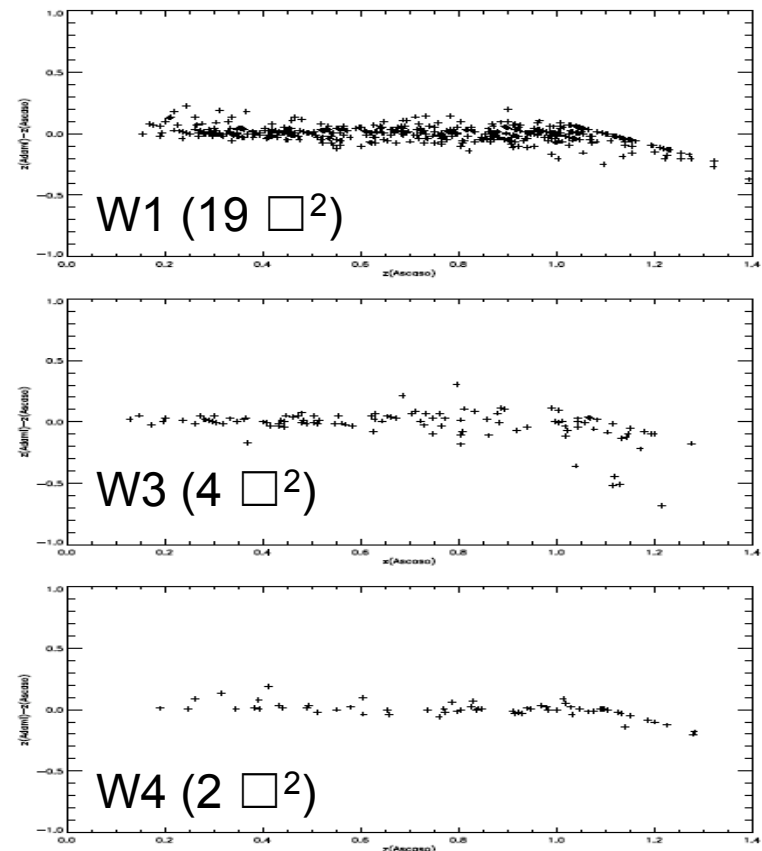
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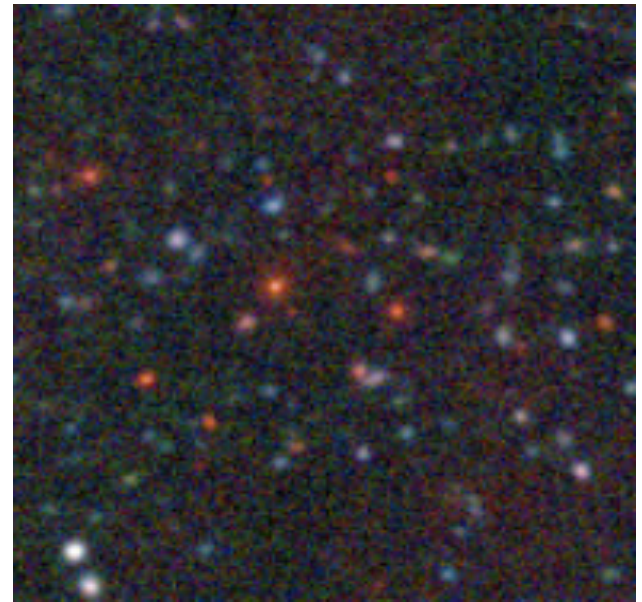
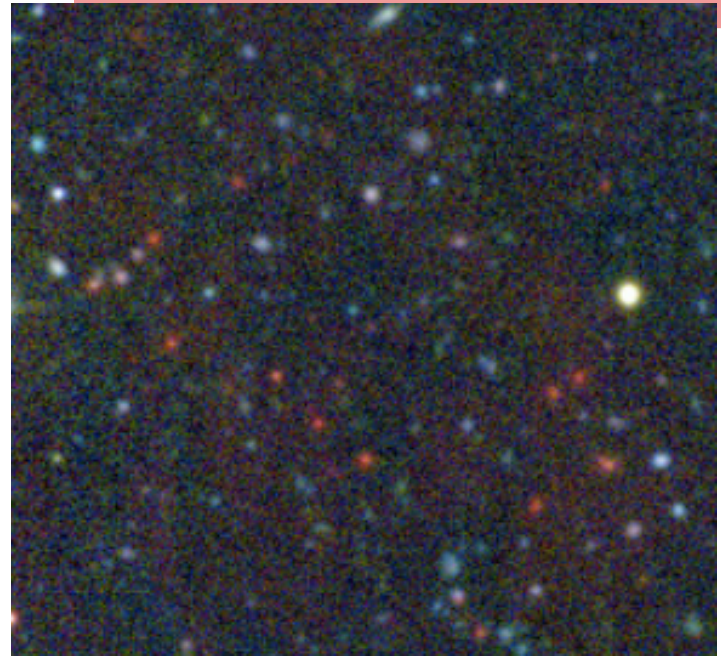
APPLICATION TO SURVEYS II: CARS

Adami et al. 2010

- They detect clusters in Wide and Deep fields.
- We obtain more than 1200 galaxy clusters in $25 \square^2$ in common, while they find ~ 600 and 1000 over 3 and 2σ resp.
- We find an agreement of 81% and 74% over 3 and 2σ resp.

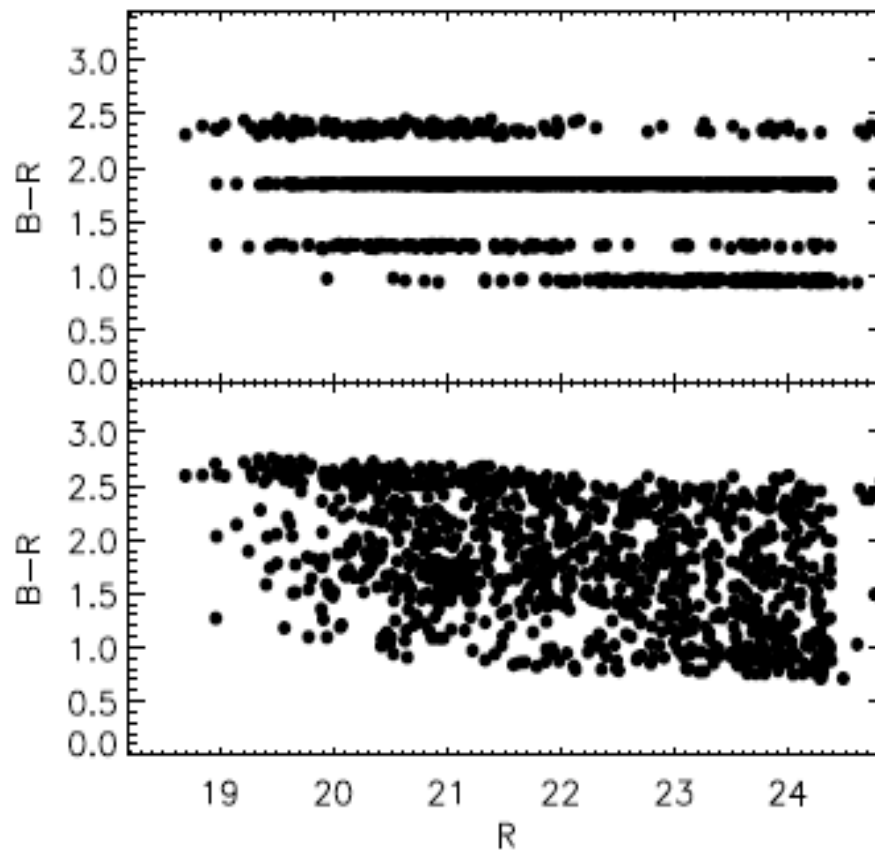
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SIMULATIONS

Color-Magnitude simulation



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THE LIKELIHOOD

- The likelihood models the probability that a galaxy with its position, photo-z, magnitude and morphological type belongs to a cluster at that position, with a given redshift and richness.
- It is the product of the model probability for
 - A cluster spatial profile: e.g., a Plummer profile.
 - A luminosity function: e.g. a Schechter function,
 - A redshift probability distribution: either from a photometric redshift software (e.g. from BPZ) or a Gaussian.

Density		Luminosity		Redshift	
Plummer		Schechter		Gaussian	
r_c (Kpc)	r_{cut} (Mpc)	α	M^*	$\langle z \rangle$ z	σ
1.25	1.25	-1.05	-21.44	0.1 - 1.2	$0.06(1+z)$

THE PRIOR

- The prior enhances the probability that a cluster exists at a given position by including any a priori information about clusters. We have considered:
 - The cluster CMR at any redshift: obtained from a set of template spectra and a fix slope. We use B-R and R-z.
 - The BCG magnitude-redshift relation: obtained from the MaxBCG sample of 13823 BCGs (*Koester et al. 2007*)

