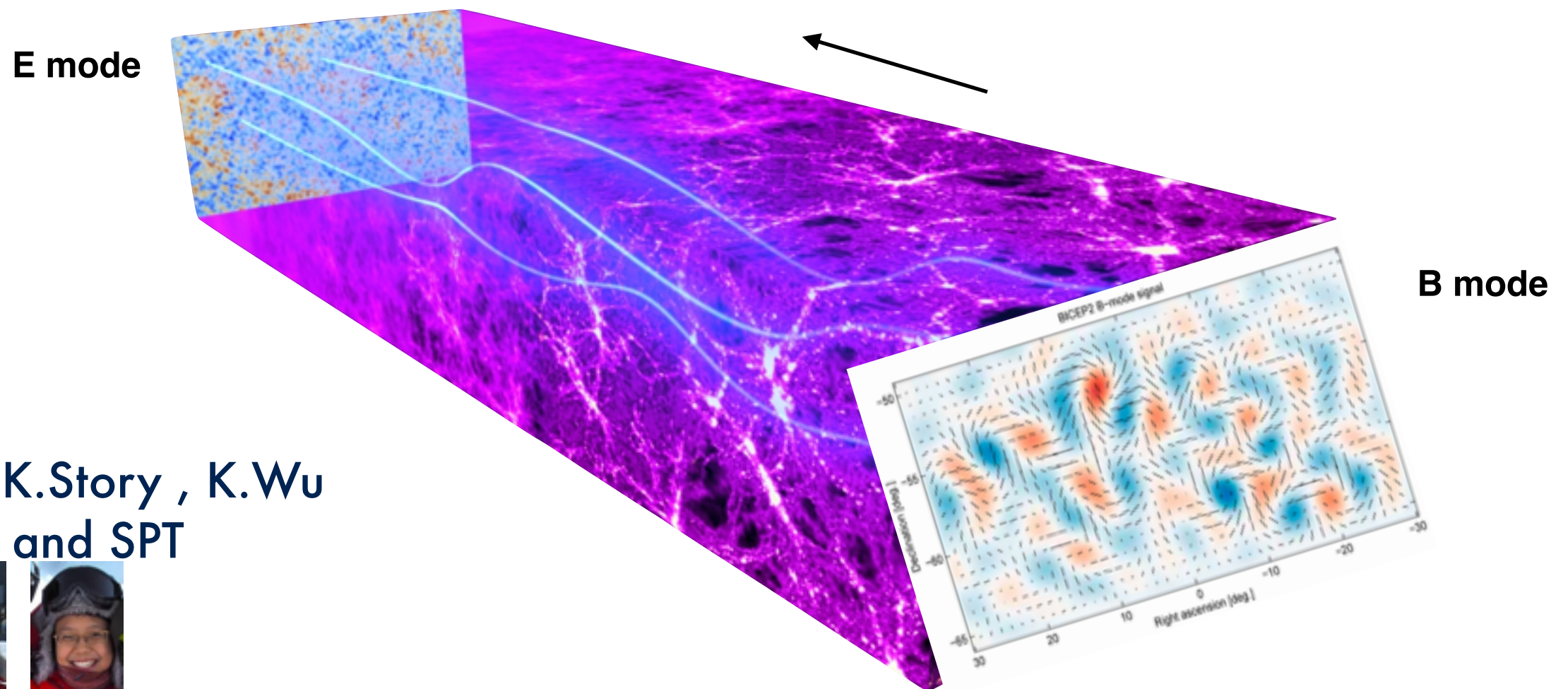


Delensing CMB B-modes: results from SPT.

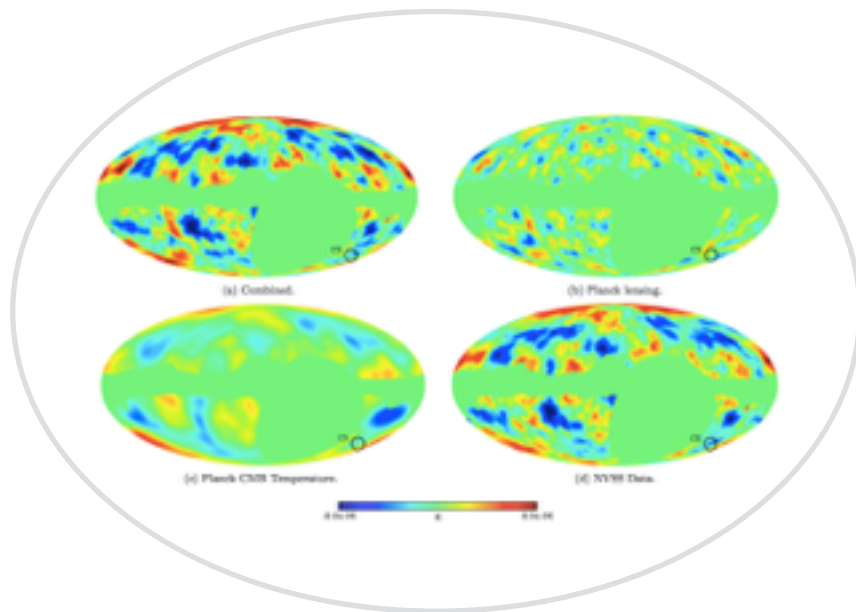


With: K.Story , K.Wu
and SPT

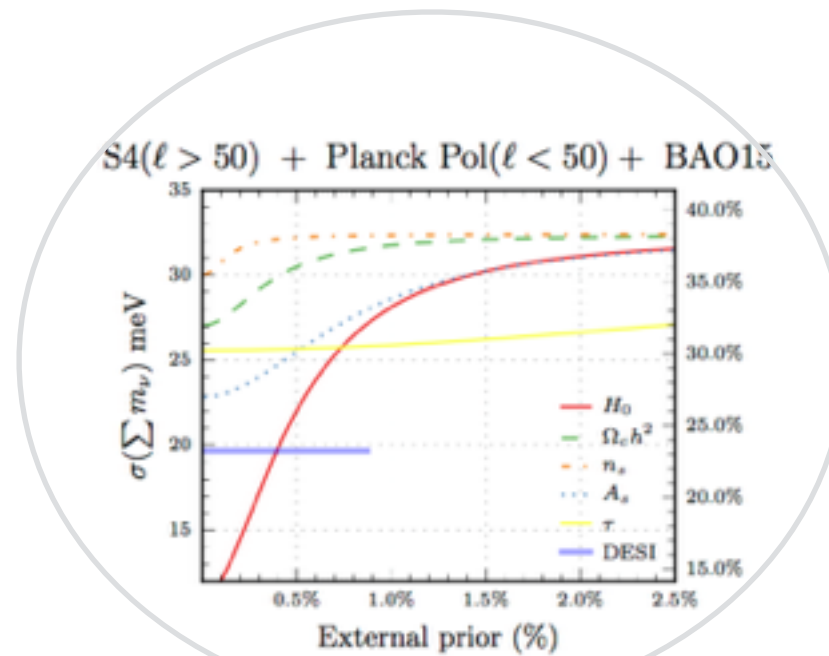


Alessandro Manzotti (KICP-U. Chicago)

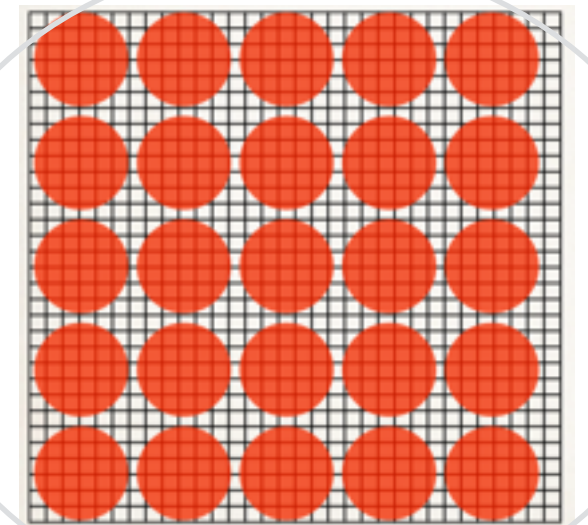
NOT IN THIS TALK: LSS AND CMB



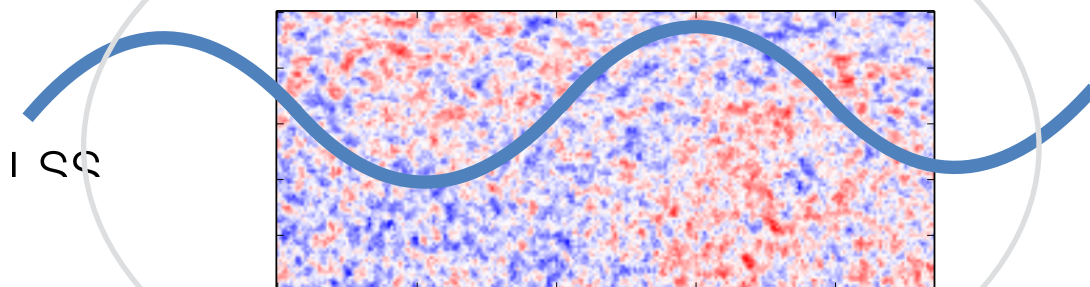
ISW map reconstruction



Future surveys forecast



LargeScaleStructure
effective field theory



Super sample effect

CosmoSIS: modular parameter
estimation

S Dodelson



W, Hu

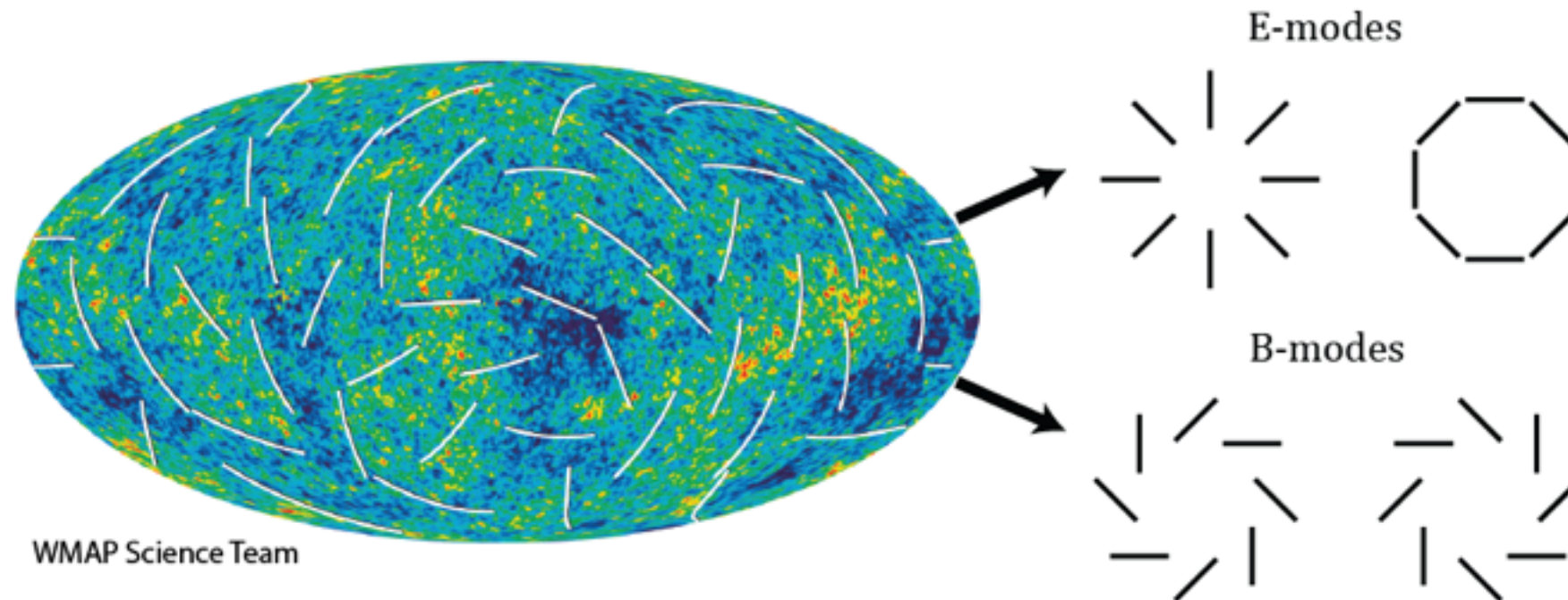


M. Pietroni

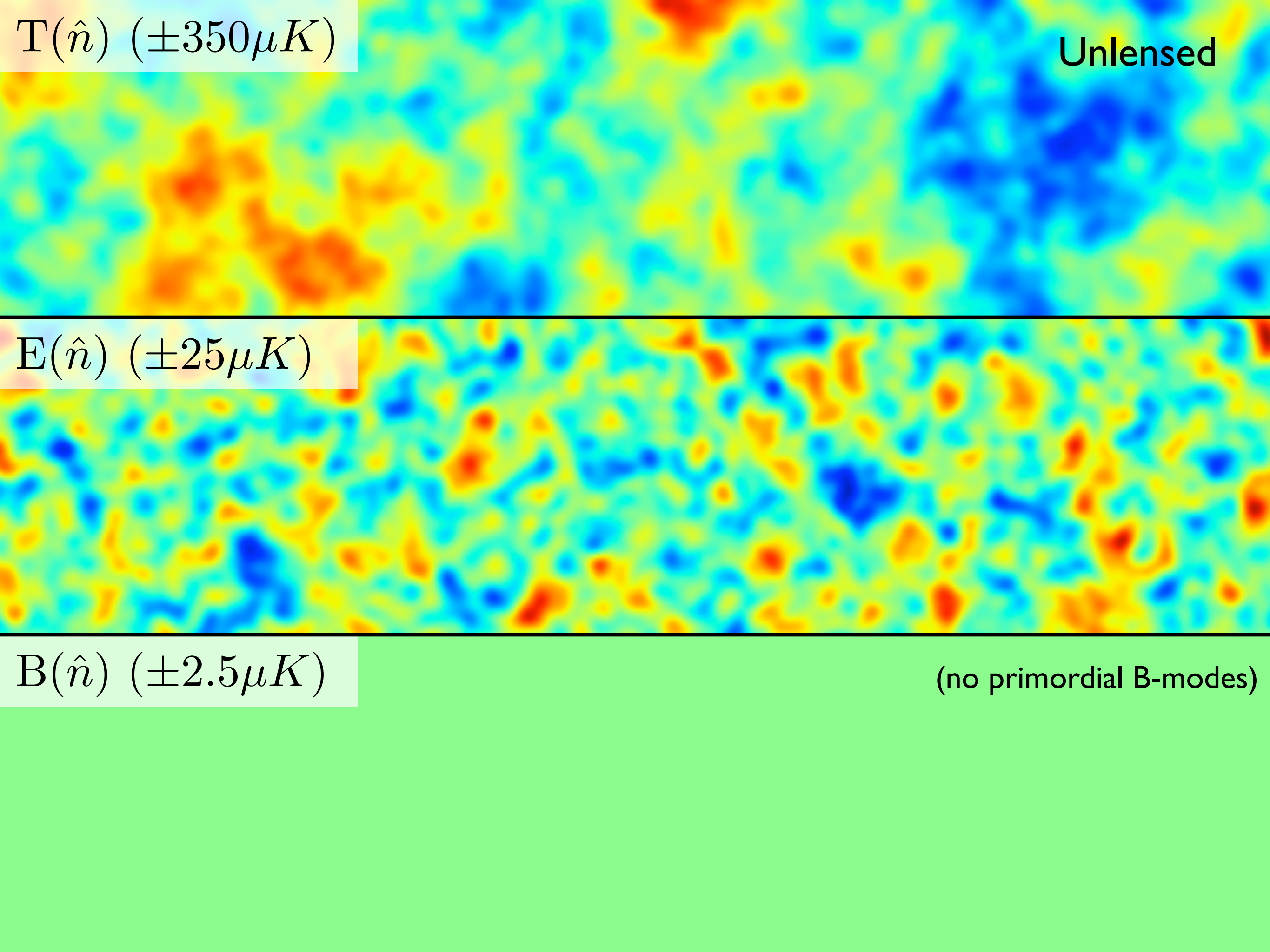


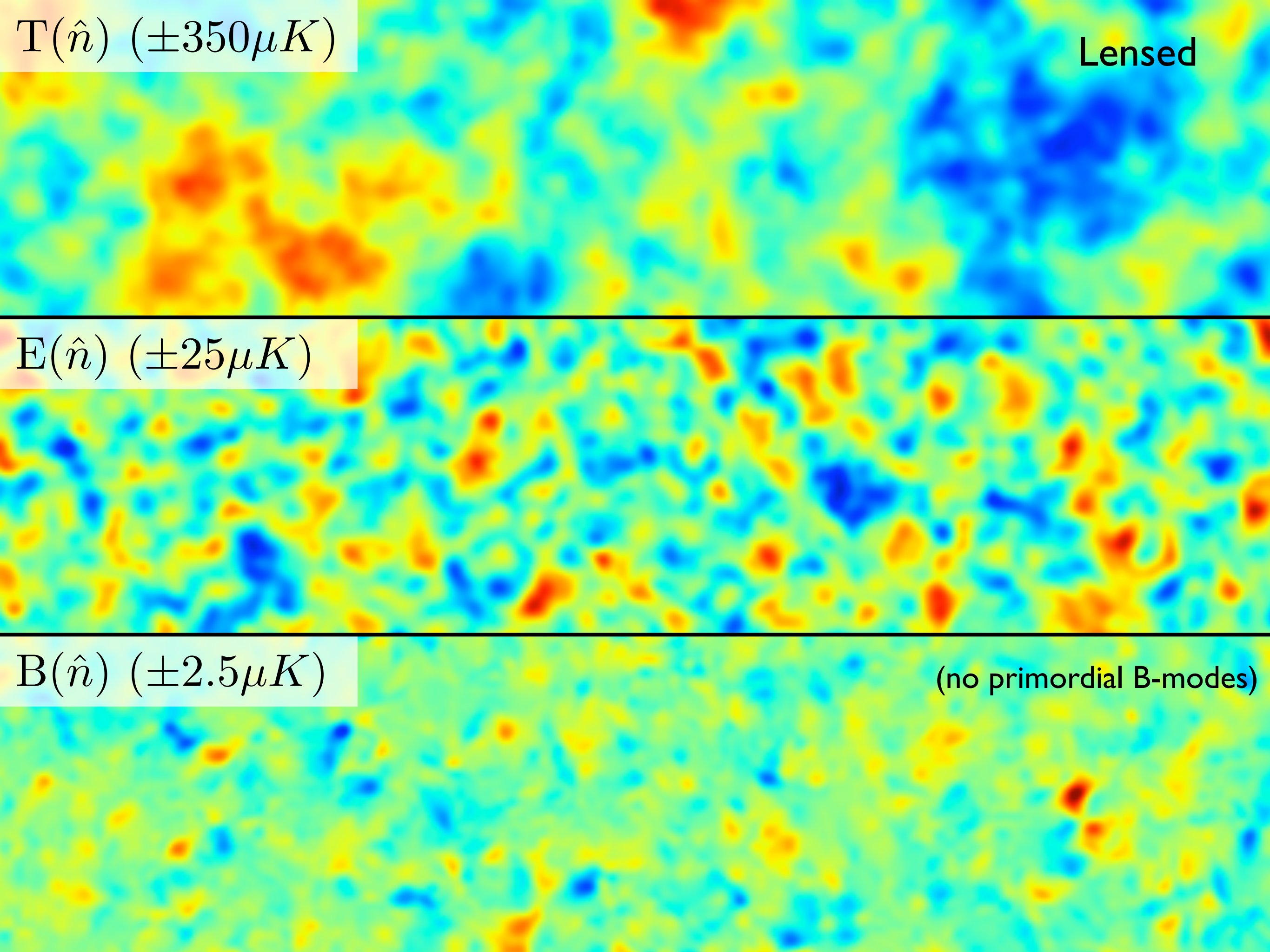
Let's talk !!

E-B DECOMPOSITION, DECOMPOSE POLARIZED CMB TO HIGHLIGHT INFLATION



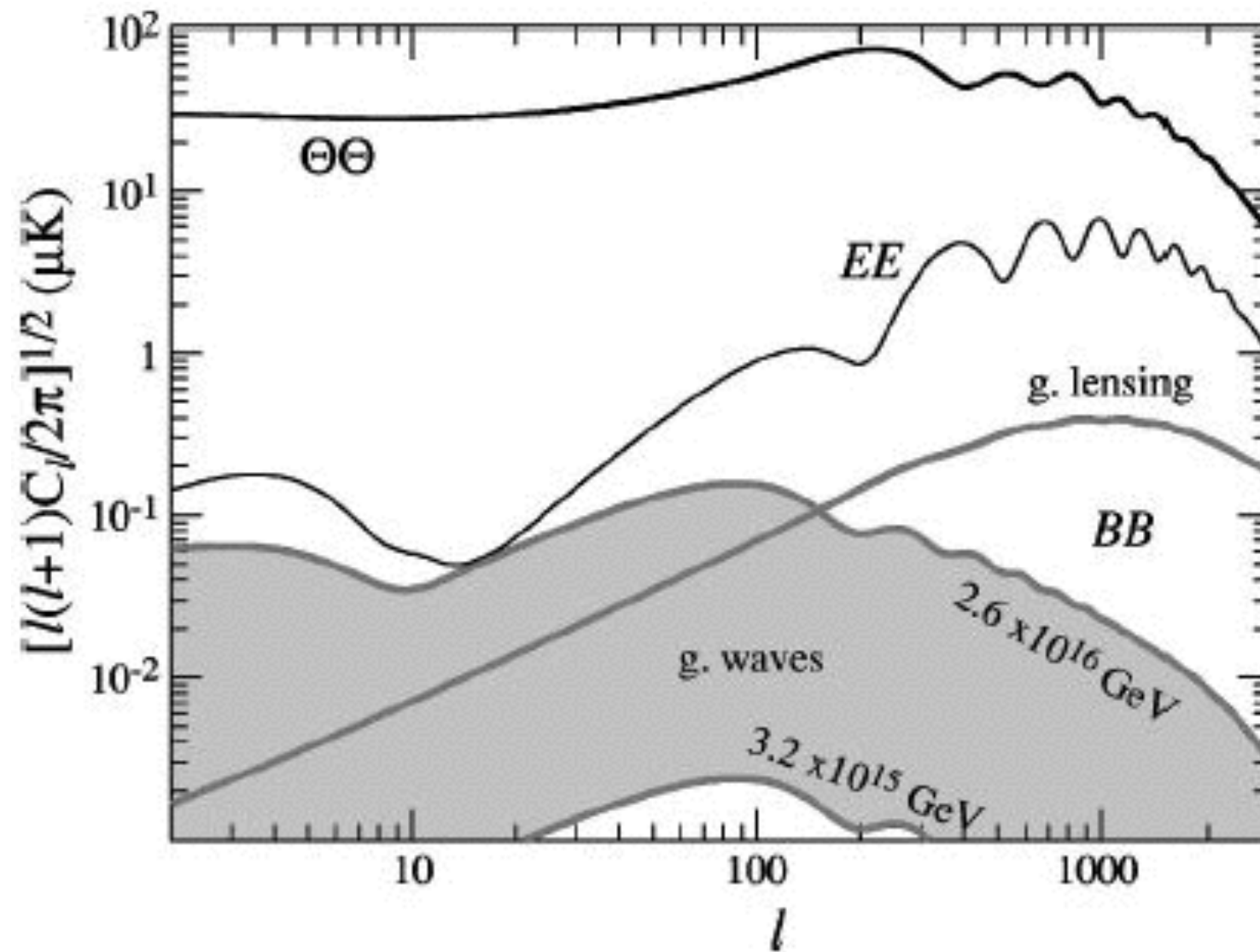
- E mode: produced by scalar anisotropies when CMB photons scatter (recombination and reionization)
- B mode: produced by tensor (gravity waves) anisotropies when CMB photons scatter (recombination and reionization)
- B mode: produced by lensing. “Turning” E mode into B mode





B-MODE LENSING SPECTRUM

Angular scale



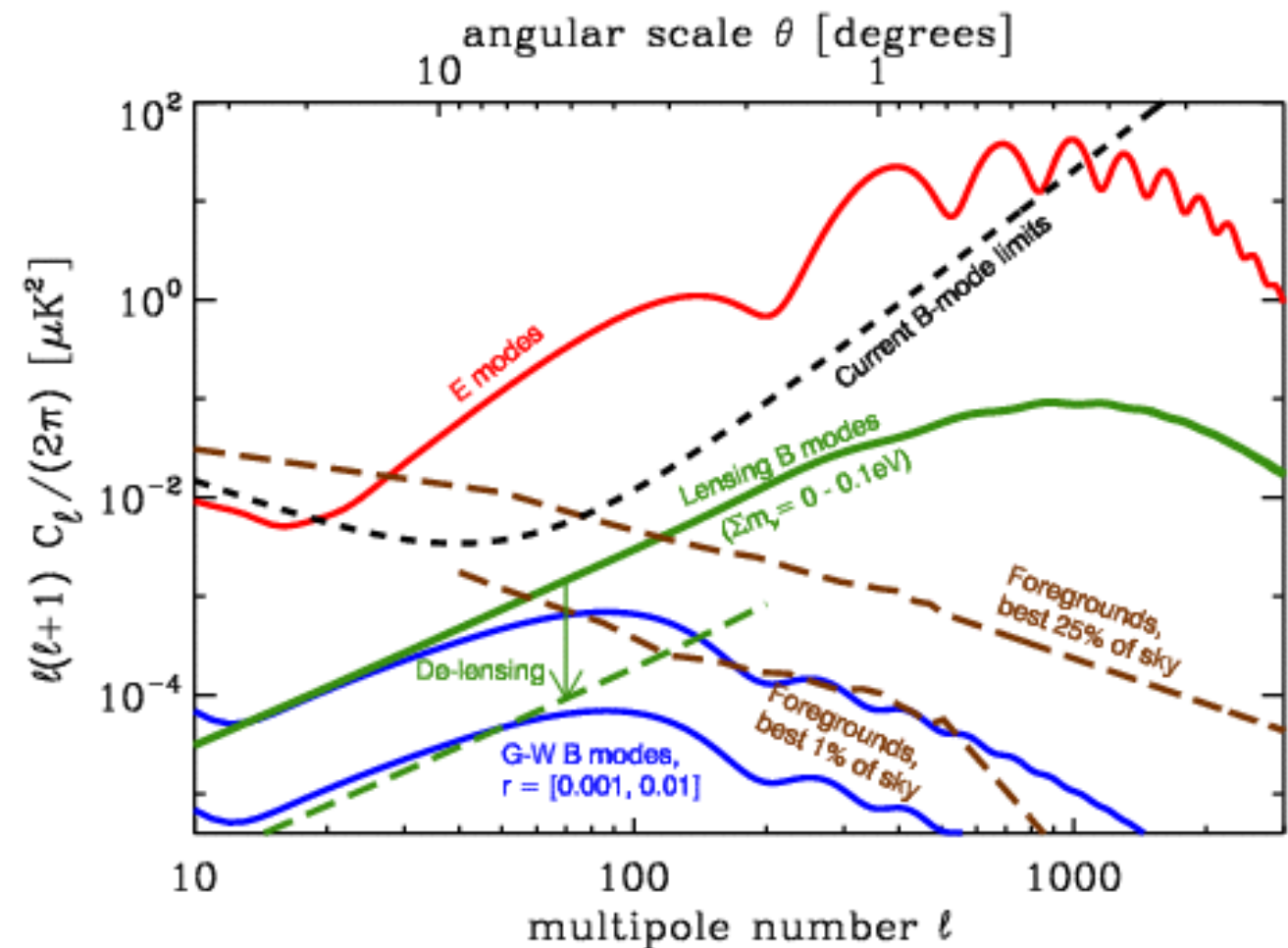
P
o
w
e
r

DELENSING IS CRUCIAL

CRUCIAL

In 10 years (CMB Stage 4) it could be the main source of noise for primordial B mode signal.

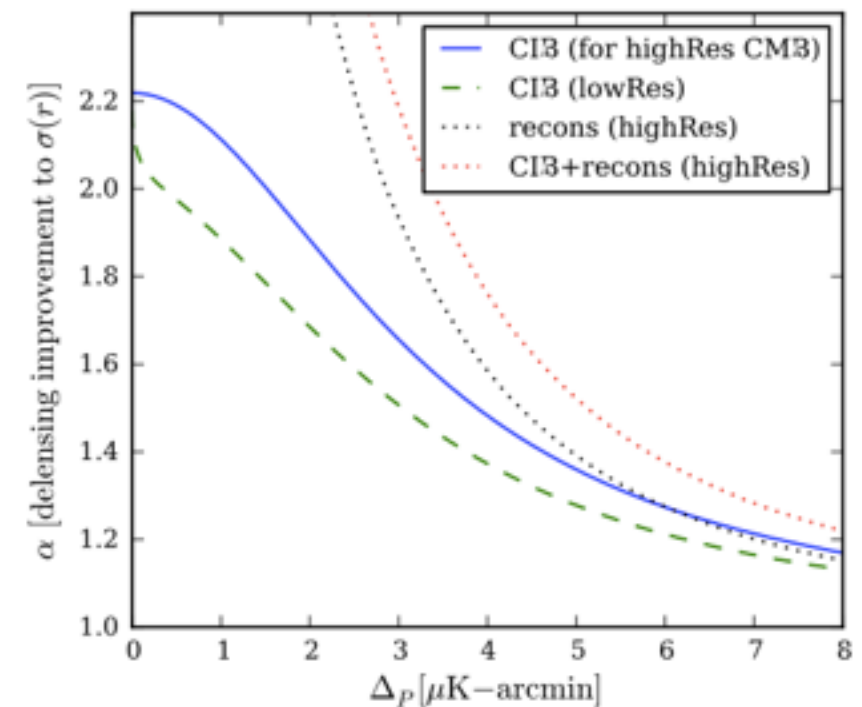
- It can be seen as a white noise component at ~ 5 $\mu\text{K-arcmin}$.
- Not cleanable with multi frequencies.
- Well modeled, but cosmic variance would be a problem



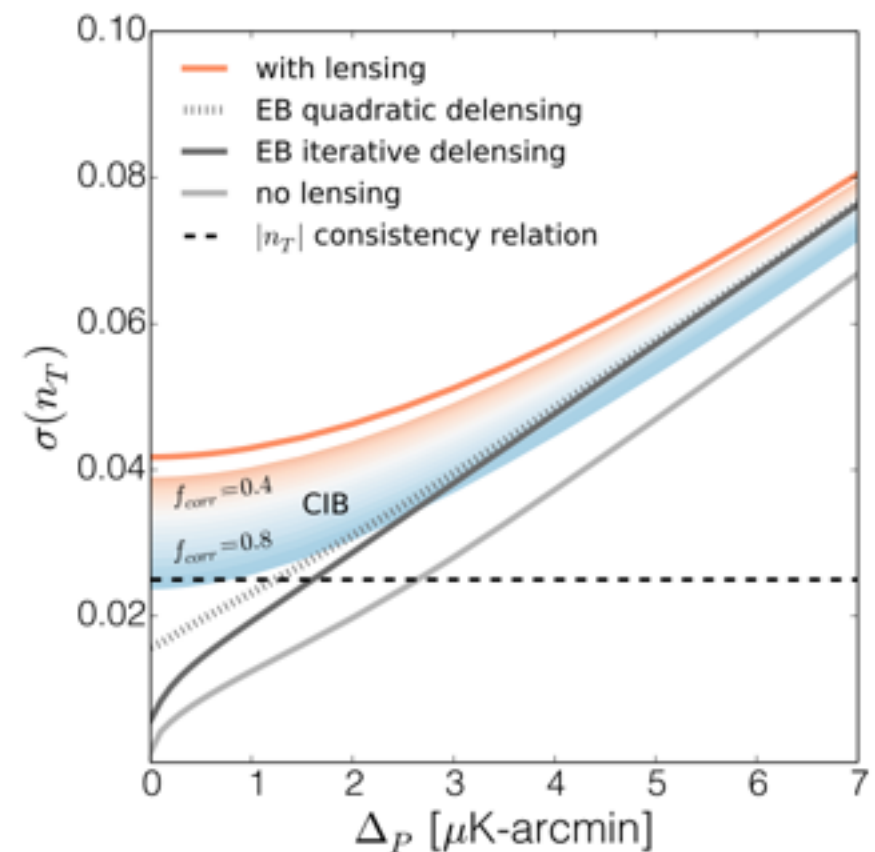
Abazajian, K.N. *et al.*

NO SURPRISE: IT WILL LIMIT INFLATIONARY CONSTRAINTS AND MORE

- Our constraint on the inflationary tensor perturbation and tilt will depend on it
- It will limit lensing reconstruction (a.k.a as iterative delensing)
- It will limit parameter that depends on peak position and damping tail information like N_{eff}

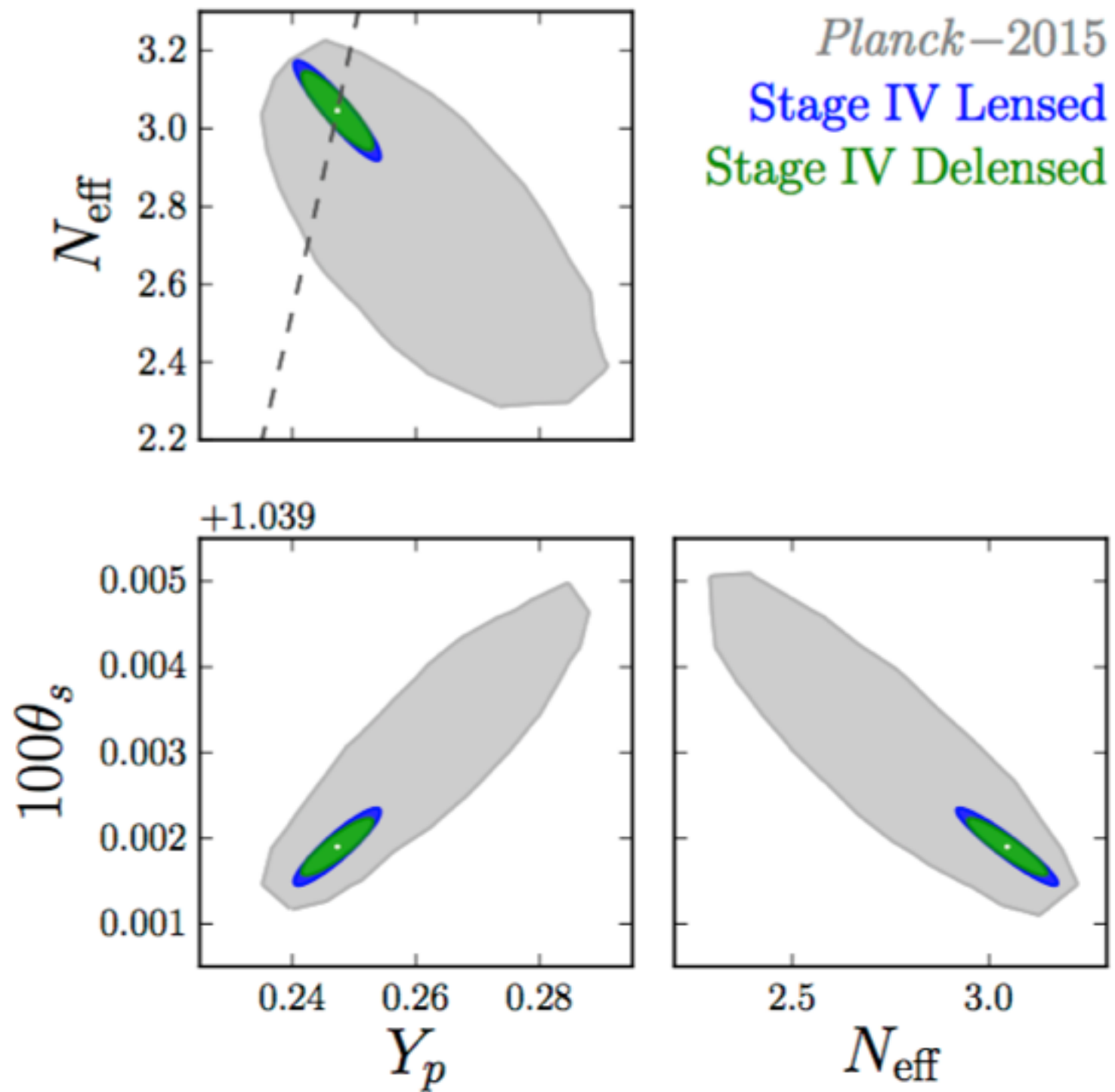


Sherwin Schmittfull.



Simard

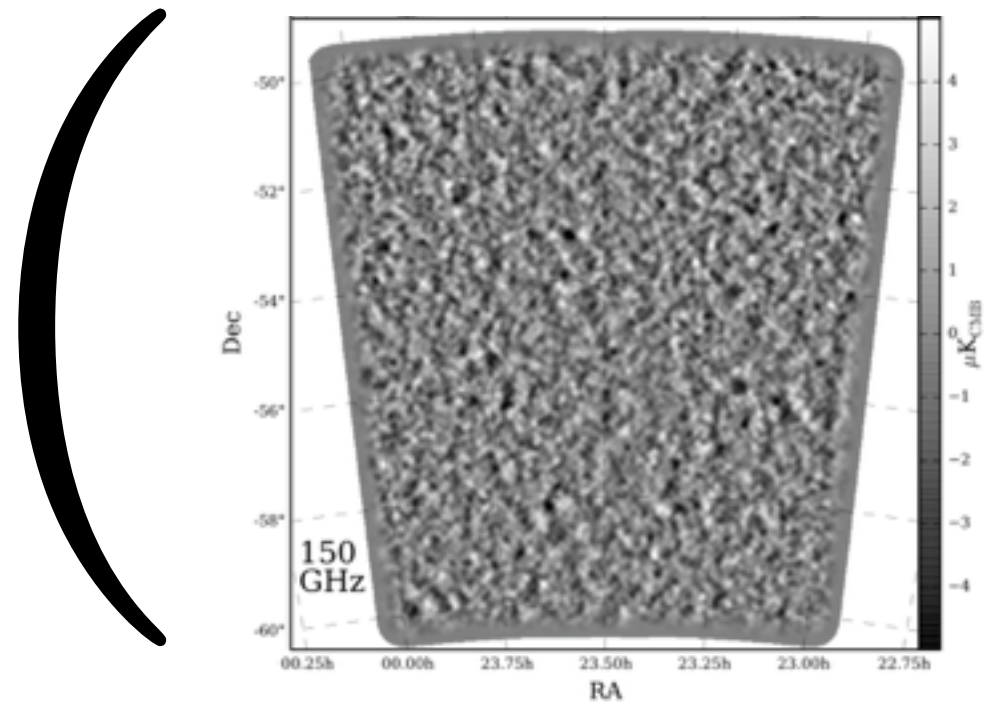
... AND MORE



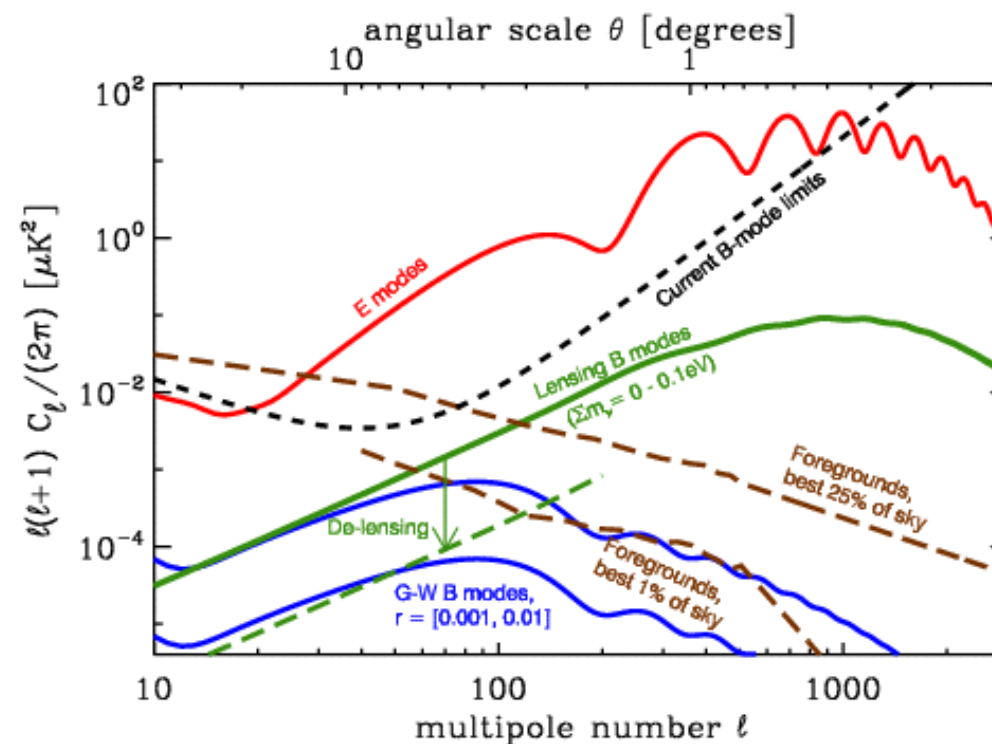
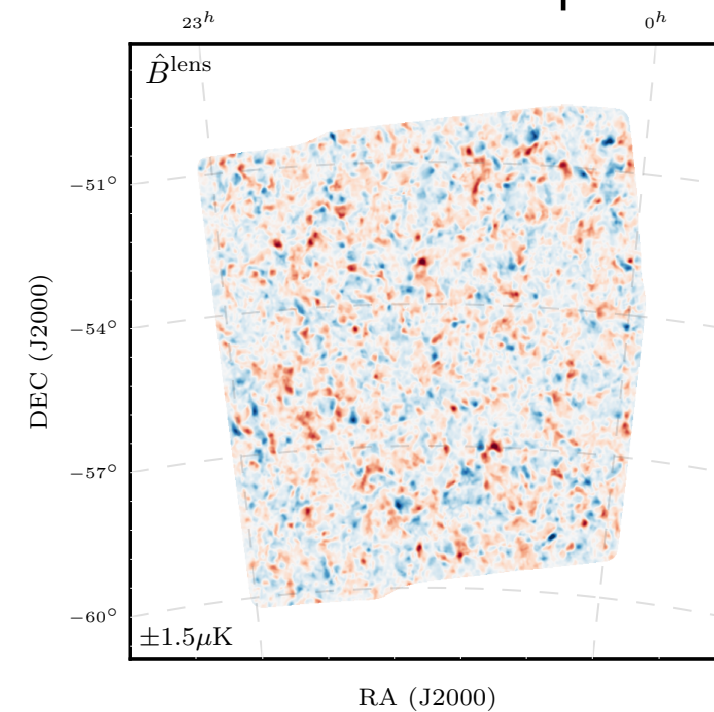
Green, Meyers, van Engelen

WHAT CAN WE DO? BUILD A TEMPLATE AND REMOVE!

B-mode data



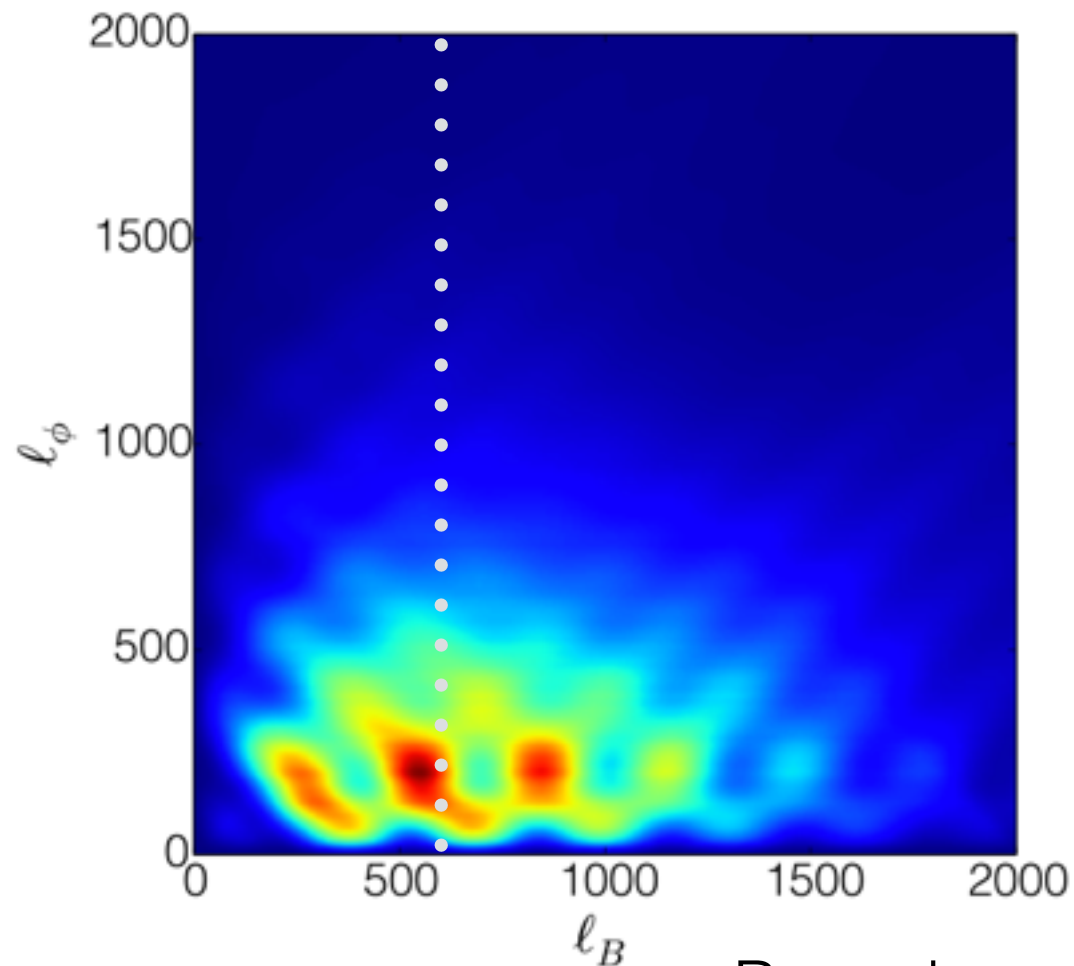
B-mode template $E \otimes \phi = B_{lens}$



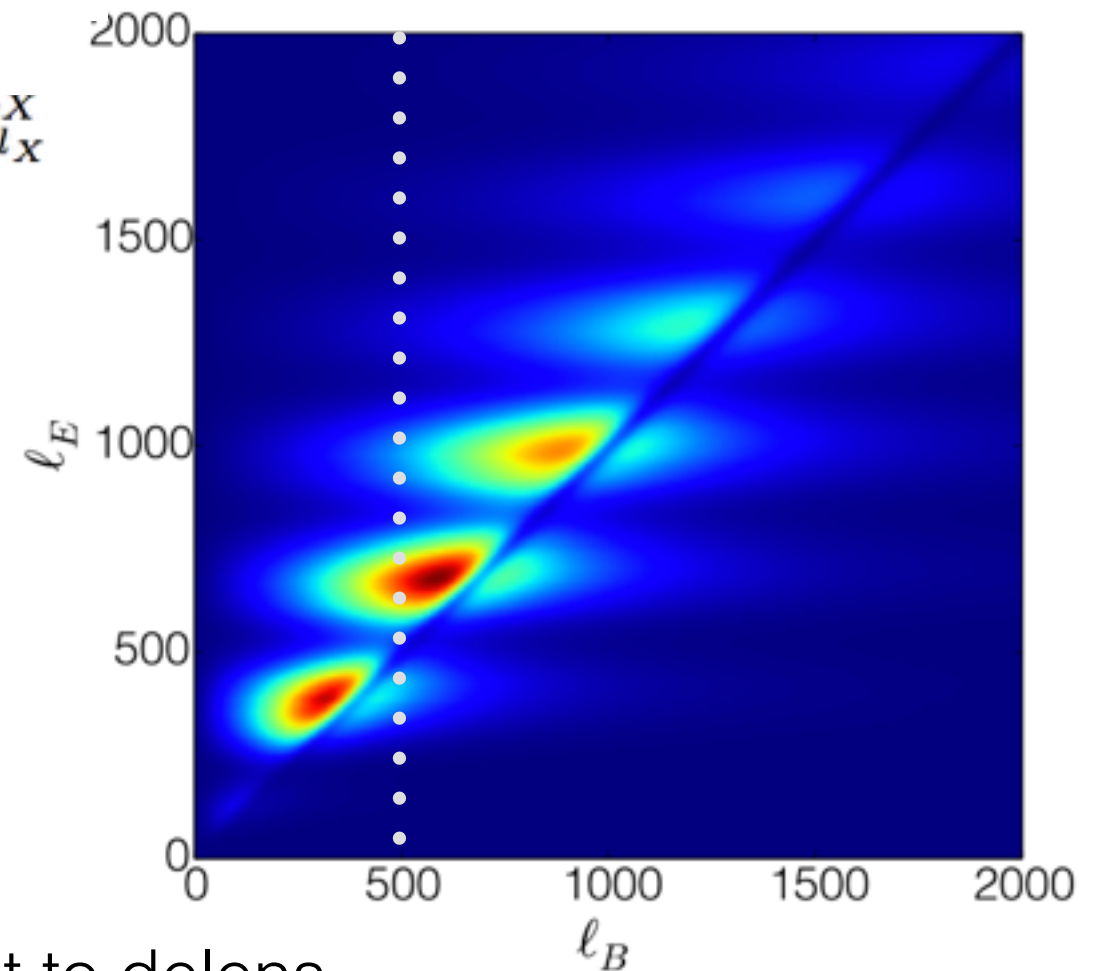
TEMPLATE: WHAT MODES DO WE NEED?

$$E \otimes \phi = B_{lens}$$

$\phi =$ Integral of structures along the line of sight



$$l_B (\partial C_{l_B}^B / \partial C_{l_X}^X) C_{l_X}^X$$



B-mode multiple you want to delens

Simard, Hanson, Holder 2014

- Mainly from large scale potential $l > 100$
- E_mode from scales slightly smaller than B_lens

HOW CAN WE GET THOSE MODES?

Your favorite
CMB experiment

$$\leftarrow E \otimes \phi = B_{lens}$$

We want

Kernel overlap

Low Noise

CIB

Cosmic Infrared Background
The **best method right now**.
Already used on data by SPT
(Hanson B-modes paper).
CIB model uncertainties not
limiting now, you can
marginalize over it (Sherwin
Schmittfull.)

CMB

In the **future** it will be the
best source of ϕ
reconstruction. Not there yet
but already powerful if
combined with the CIB

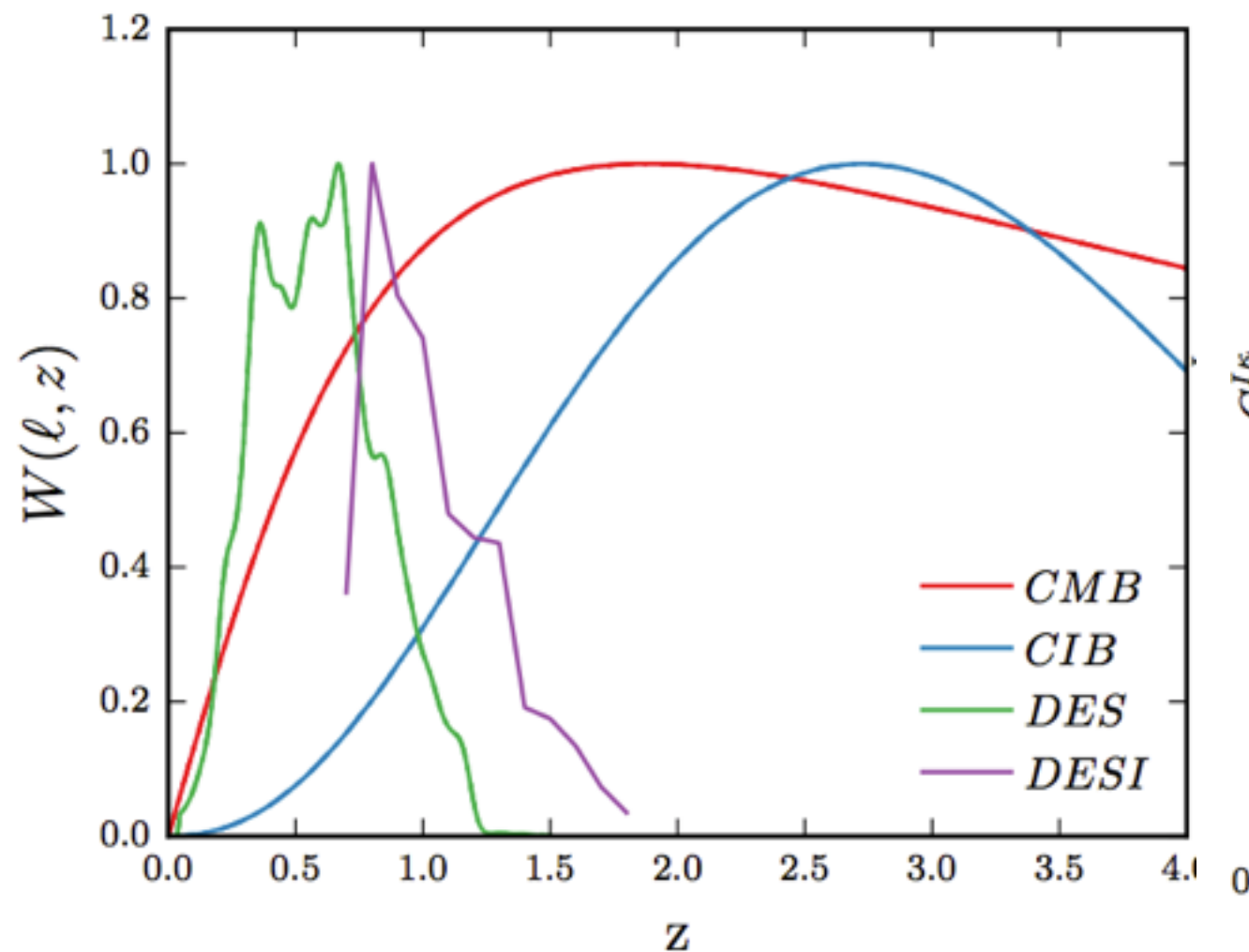
Galaxies

Low redshift. They do
not probe well the
sources that lens the
CMB. Maybe useful to
check for systematics.

SKA?

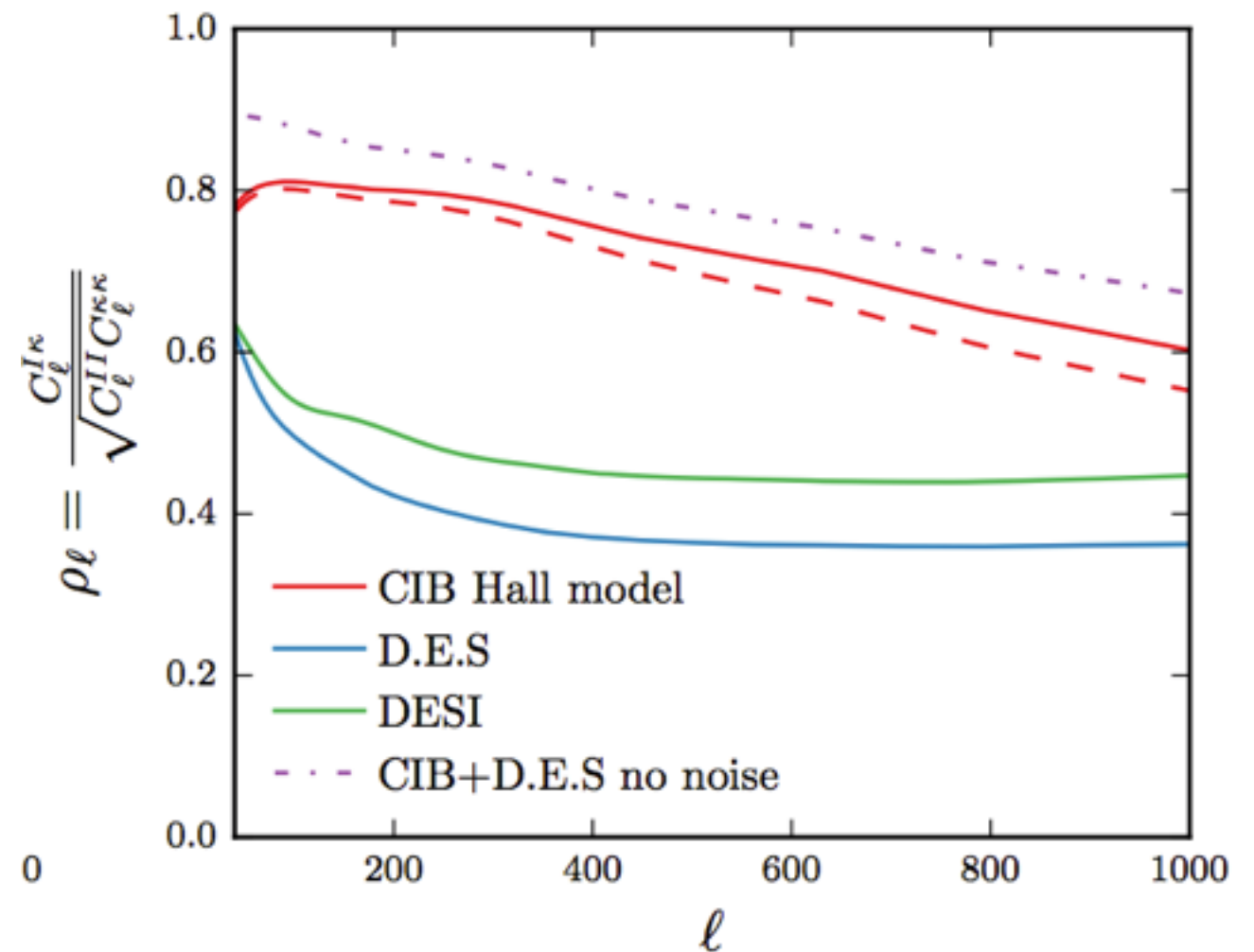
OPTIMAL SOURCE FOR A LENSING MAP?

Where the lenses are



Redshift

How much are they correlated with lensing considering noise



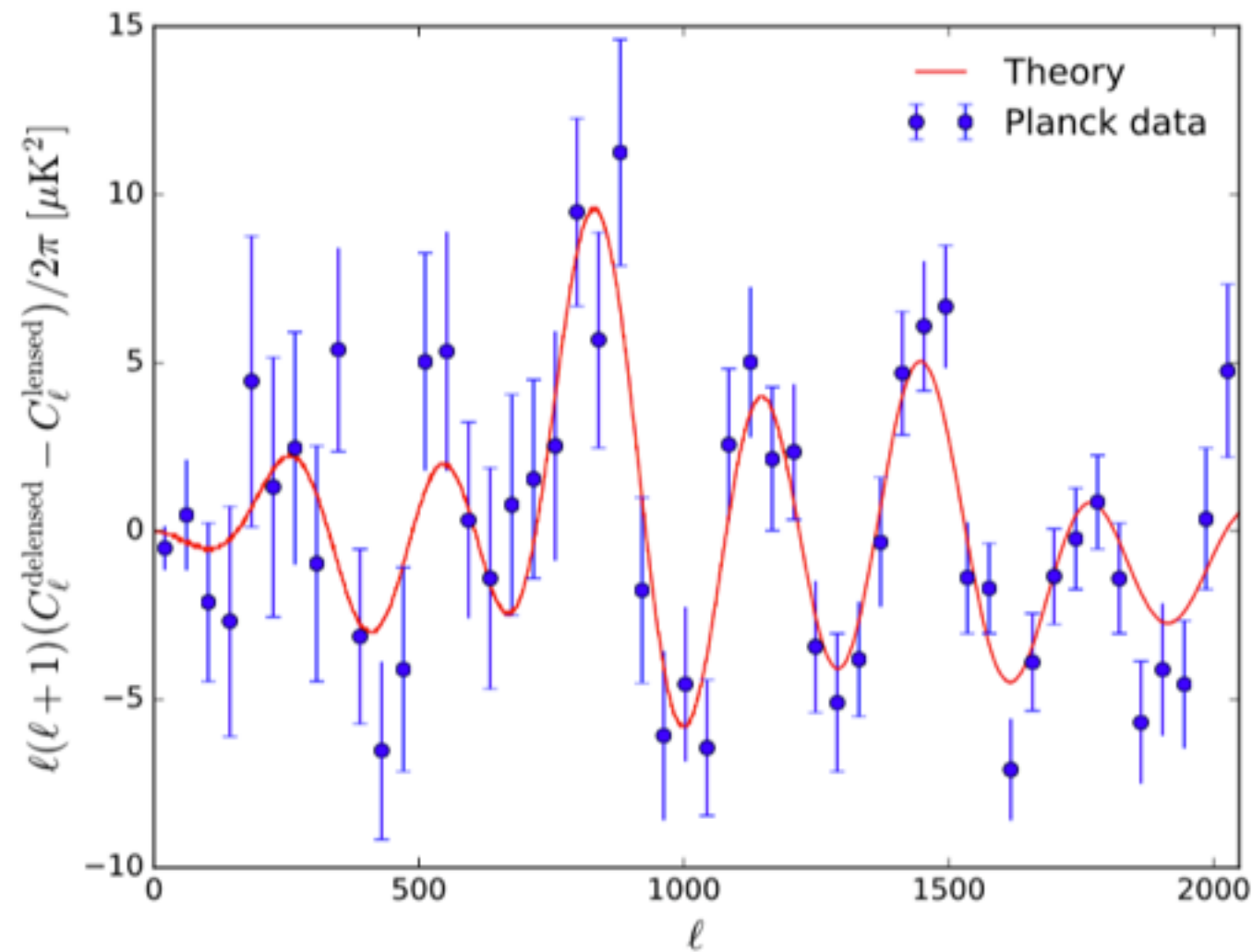
Angular Scale

DELENSING IS CRUCIAL, FEASIBLE BUT HARD.

**HOWEVER A NEW PHASE IS BEGINNING:
WE ARE NOW DELENSING**

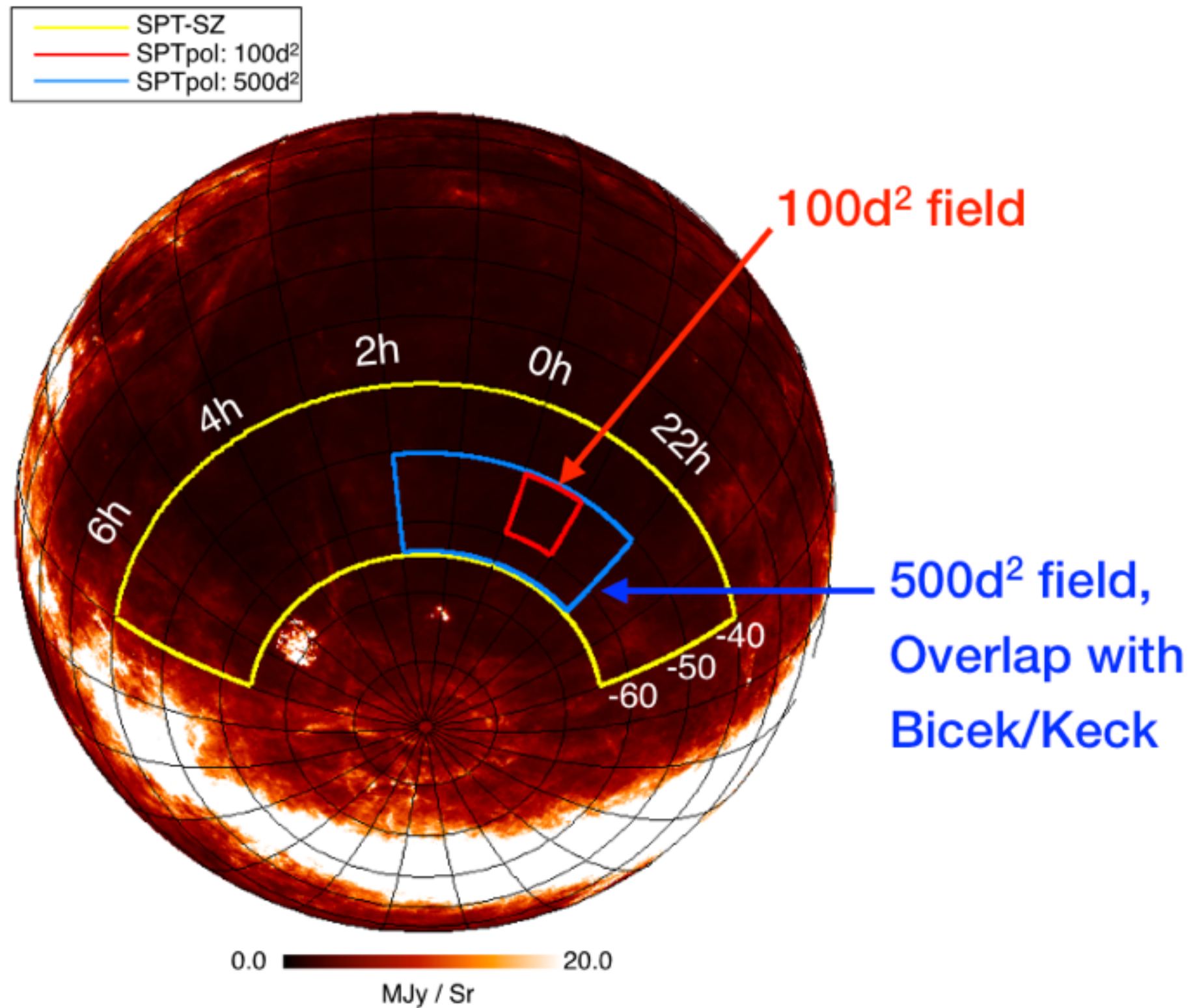
A (QUITE LOCAL) SUCCESS IN TEMPERATURE

Real space CIB delensing of Planck TT data.



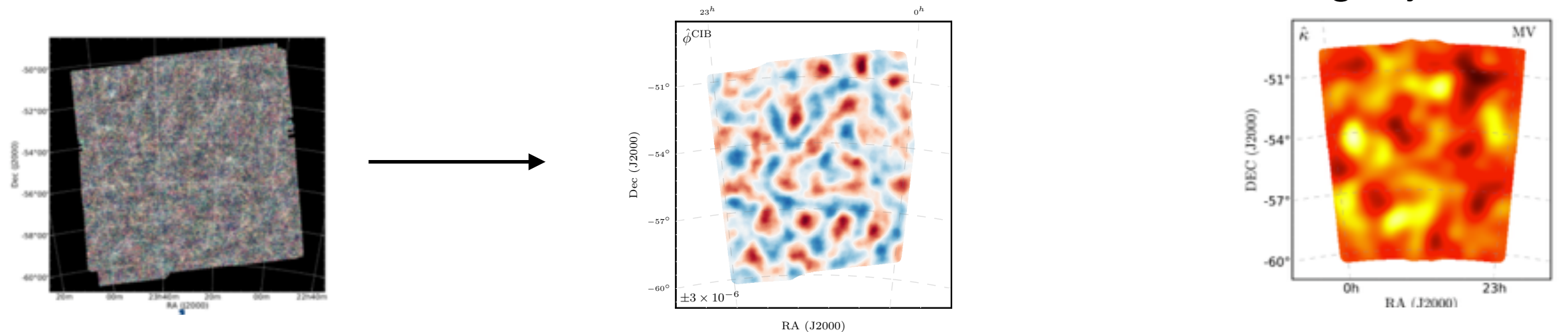
Patricia Larsen, Anthony Challinor, Blake D. Sherwin, Daisy Mak

THE SOUTH POLE TELESCOPE STORY, DELENSING THE B-MODES

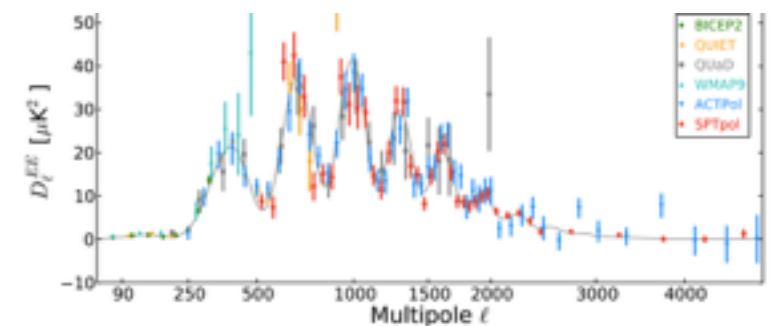
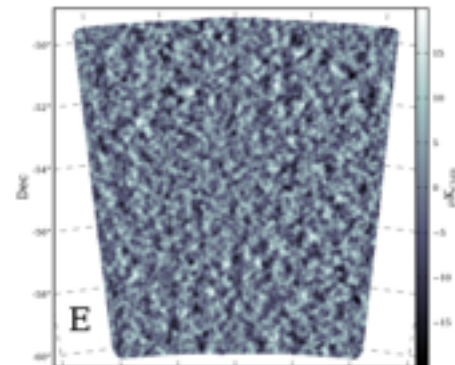


THE SPT STORY, THE DATA

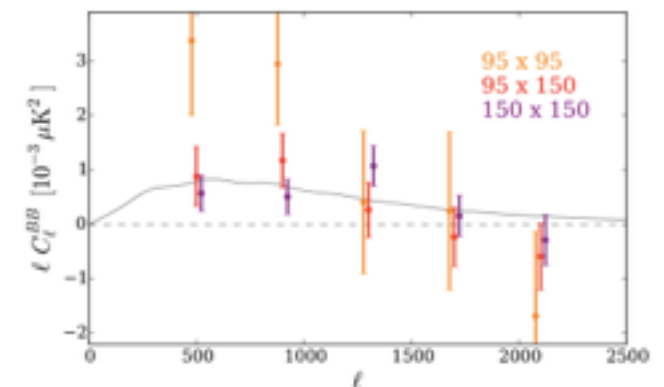
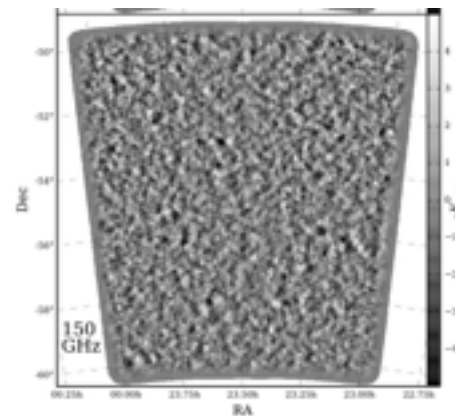
- CIB map, from Herschel 500 μ m map.



- E mode (Crites, SPT 2015)



- B mode (Keisler, SPT 2015)



B TEMPLATE: THE PIPELINE

Construct a lensing template from the CIB map

$$\hat{\phi} = C_{\ell}^{CIB-\phi} (C_{\ell}^{\phi\phi} C_{\ell}^{CIB-CIB})^{-1} T_{\ell}^{CIB}$$

Filter the E-mode map with a C-inv
Wiener filter: $\ell_{\min}^x \ell_{\max}$

Build a B template

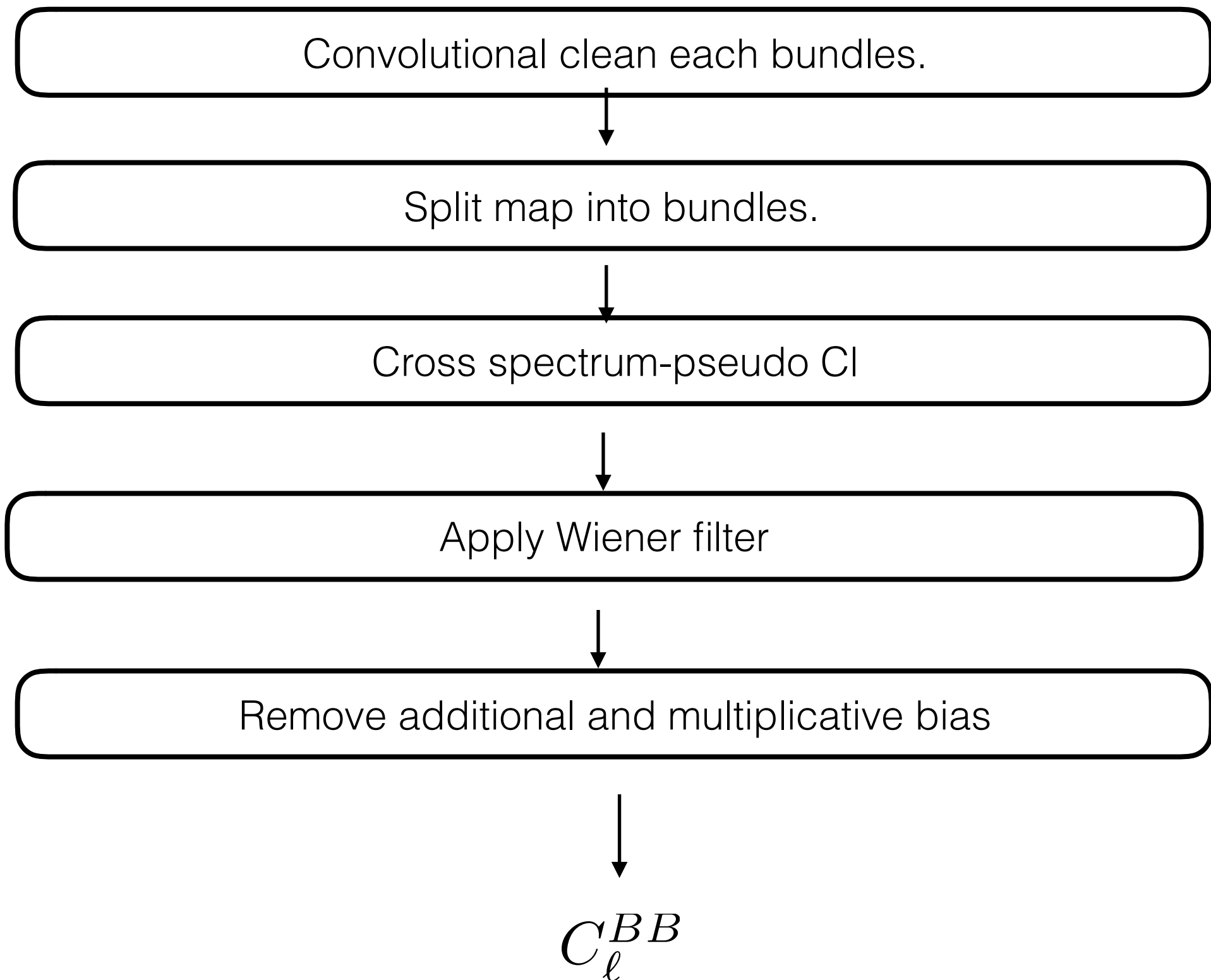
$$B^{\text{lens}}(\mathbf{l}) = \int \frac{d^2\mathbf{l}'}{(2\pi)^2} W(\mathbf{l}, \mathbf{l}') E(\mathbf{l}') \kappa(\mathbf{l} - \mathbf{l}')$$

Make it as similar as possible to the data. Apply Transfer function

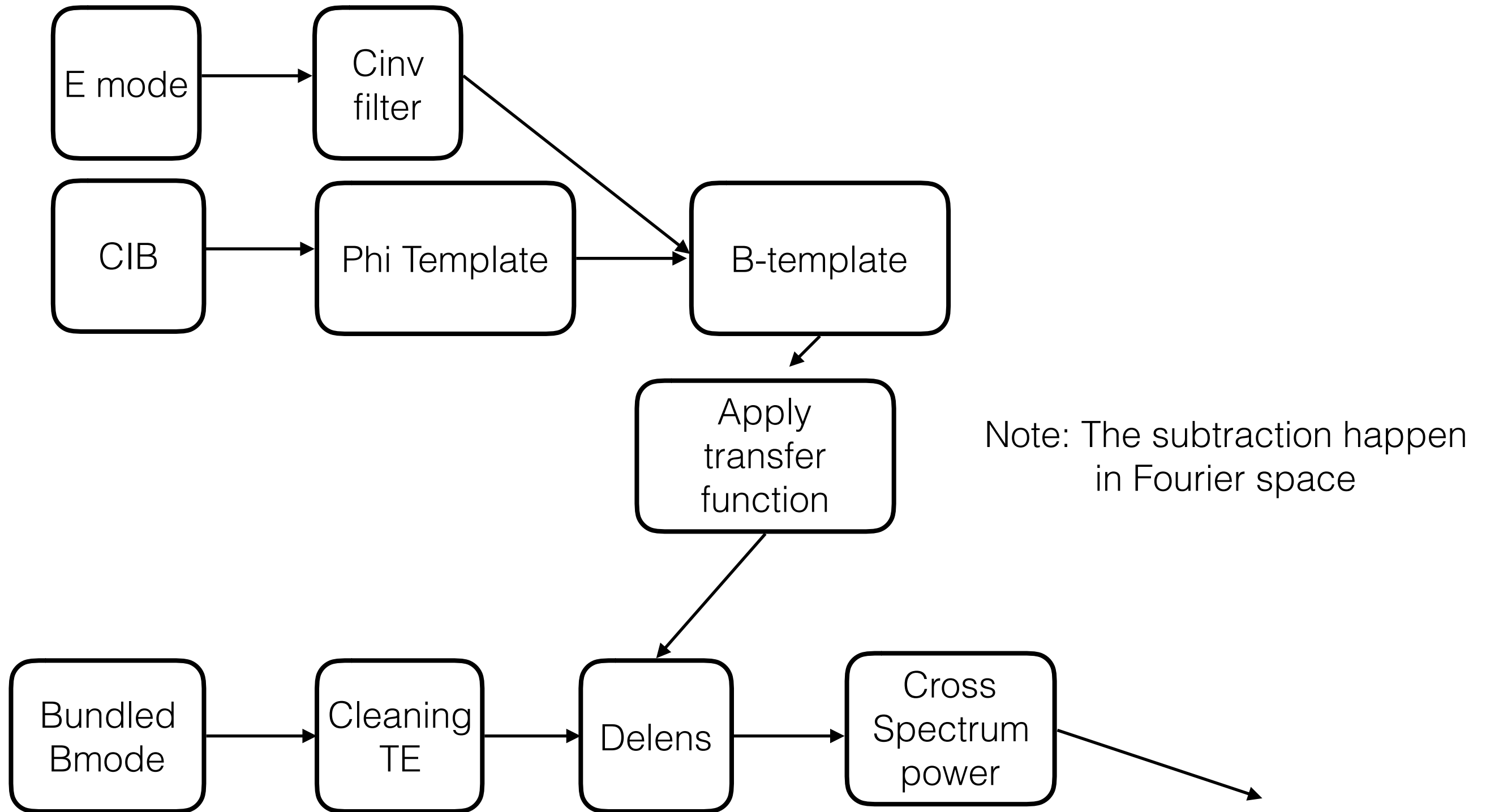
$$\bar{B}_{\text{lens}}$$

Note: This is a signal to noise
filtered template

BB POWER: THE PIPELINE



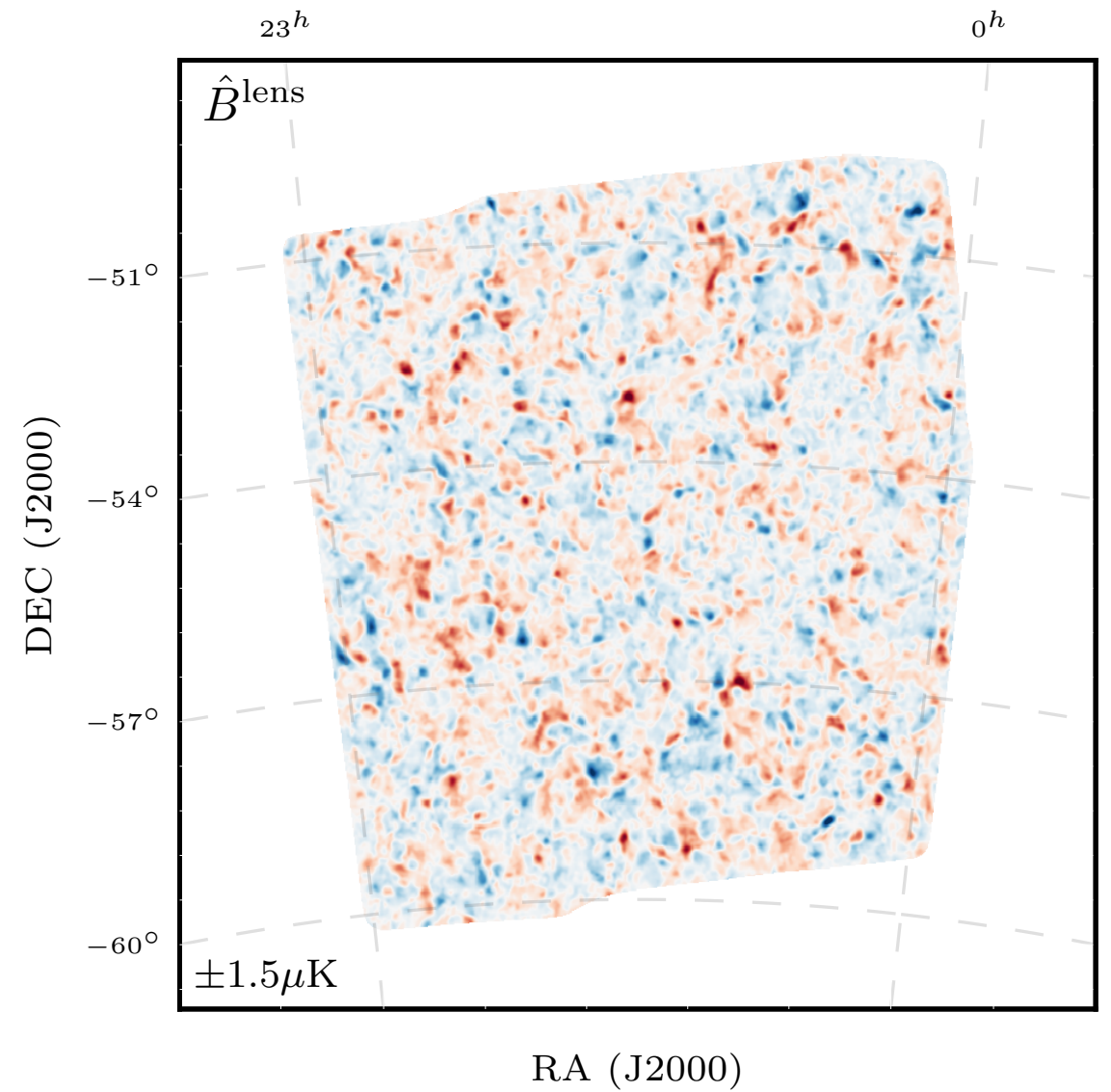
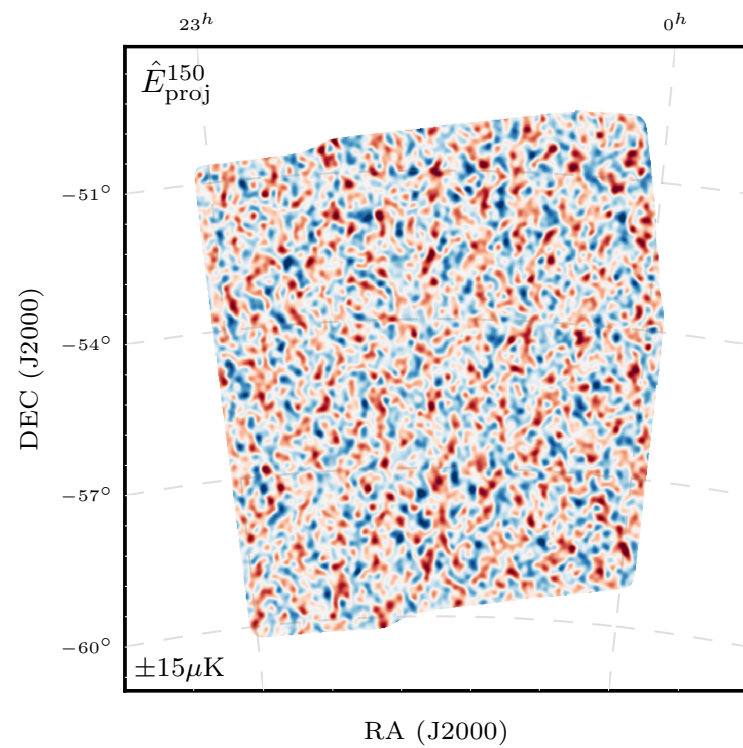
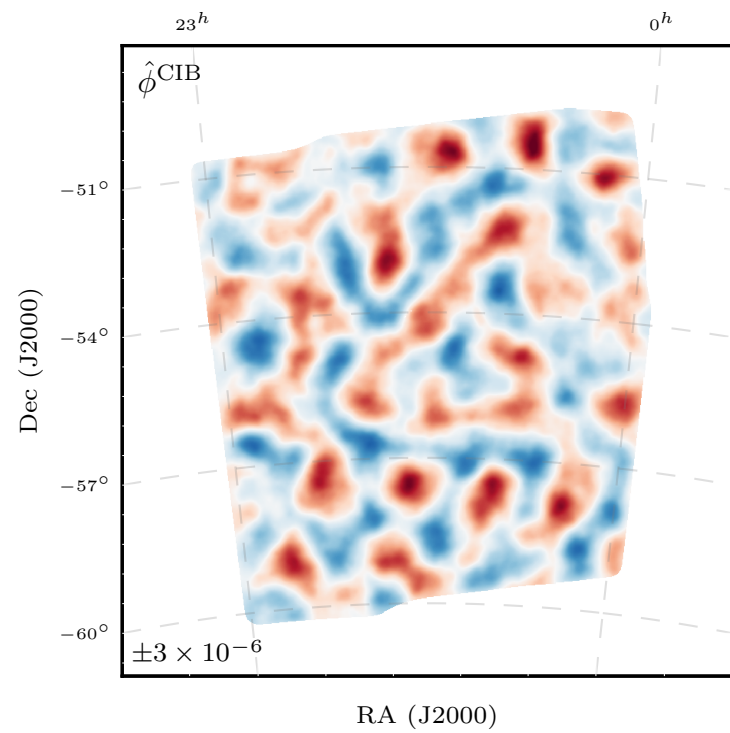
PUTTING THEM TOGETHER : DELENSING PIPELINE



$$B^{\text{res}}(\ell) = B^{\text{lens}}(\ell) - \hat{B}^{\text{lens}}(\ell)$$

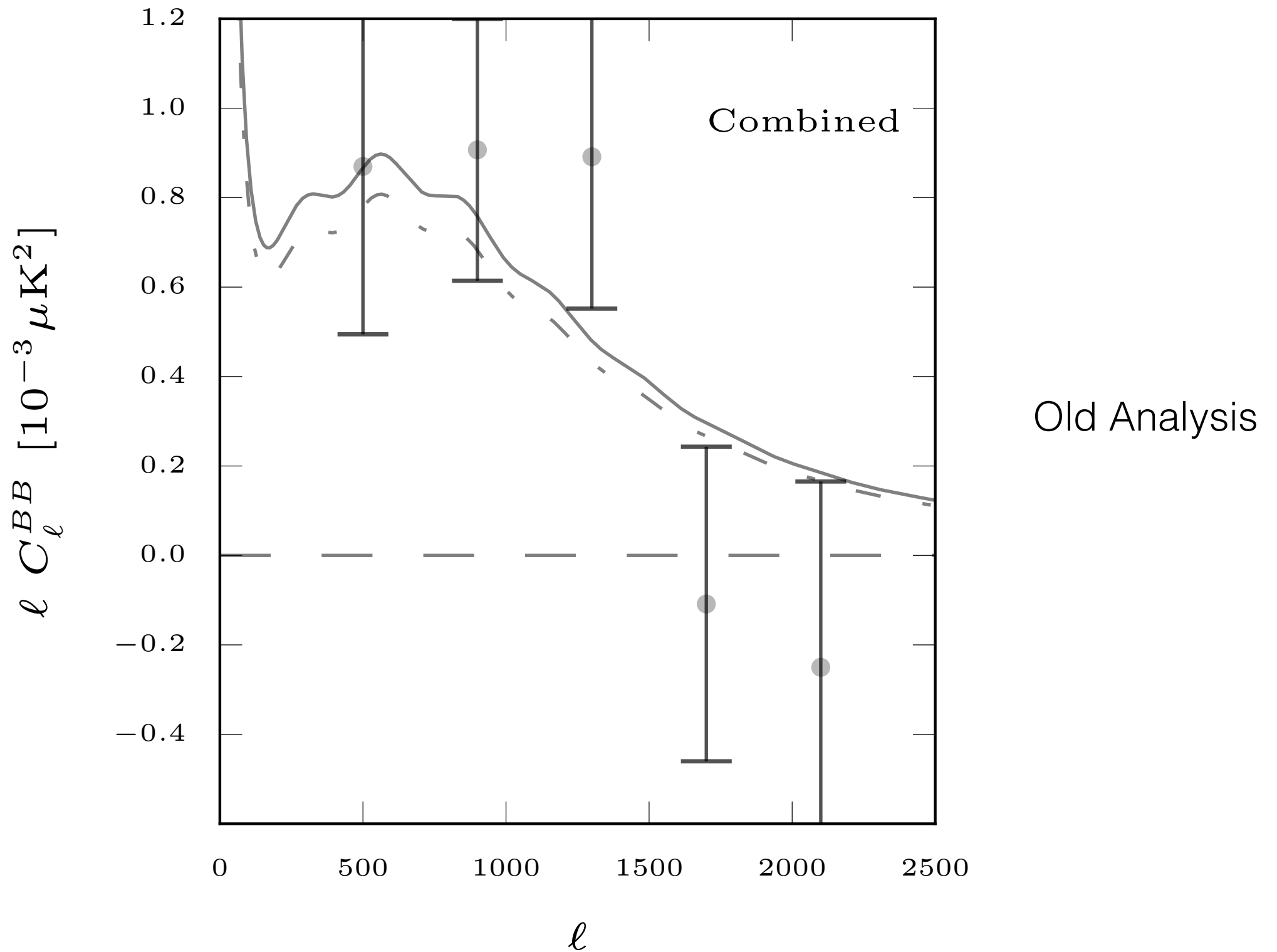
DATA

SPT 15-20% DELENSING: THE MAPS

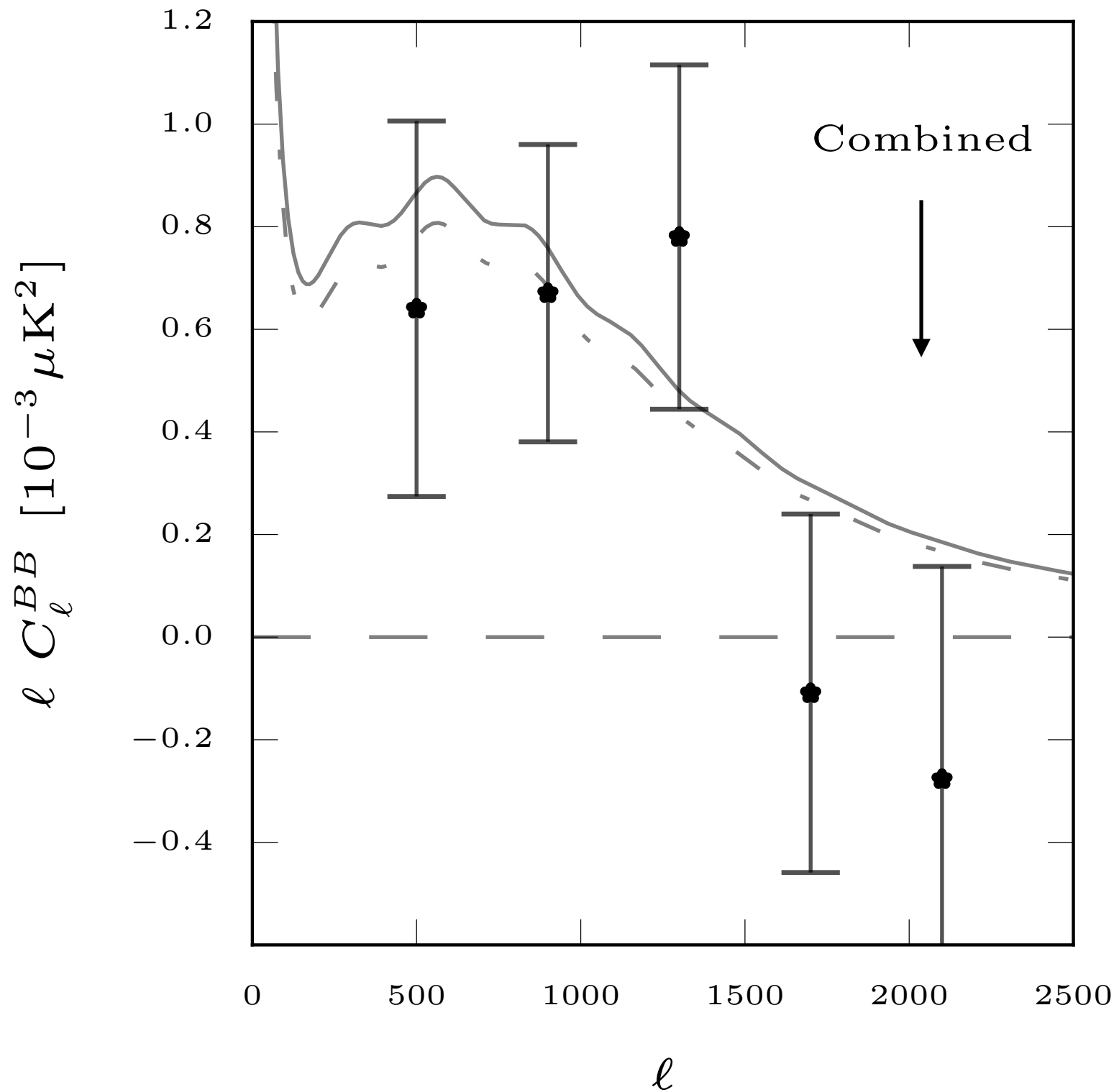


Work 2 years on simulations, filtering ...

SPT 15-20% DELENSING: THE BAND POWERS

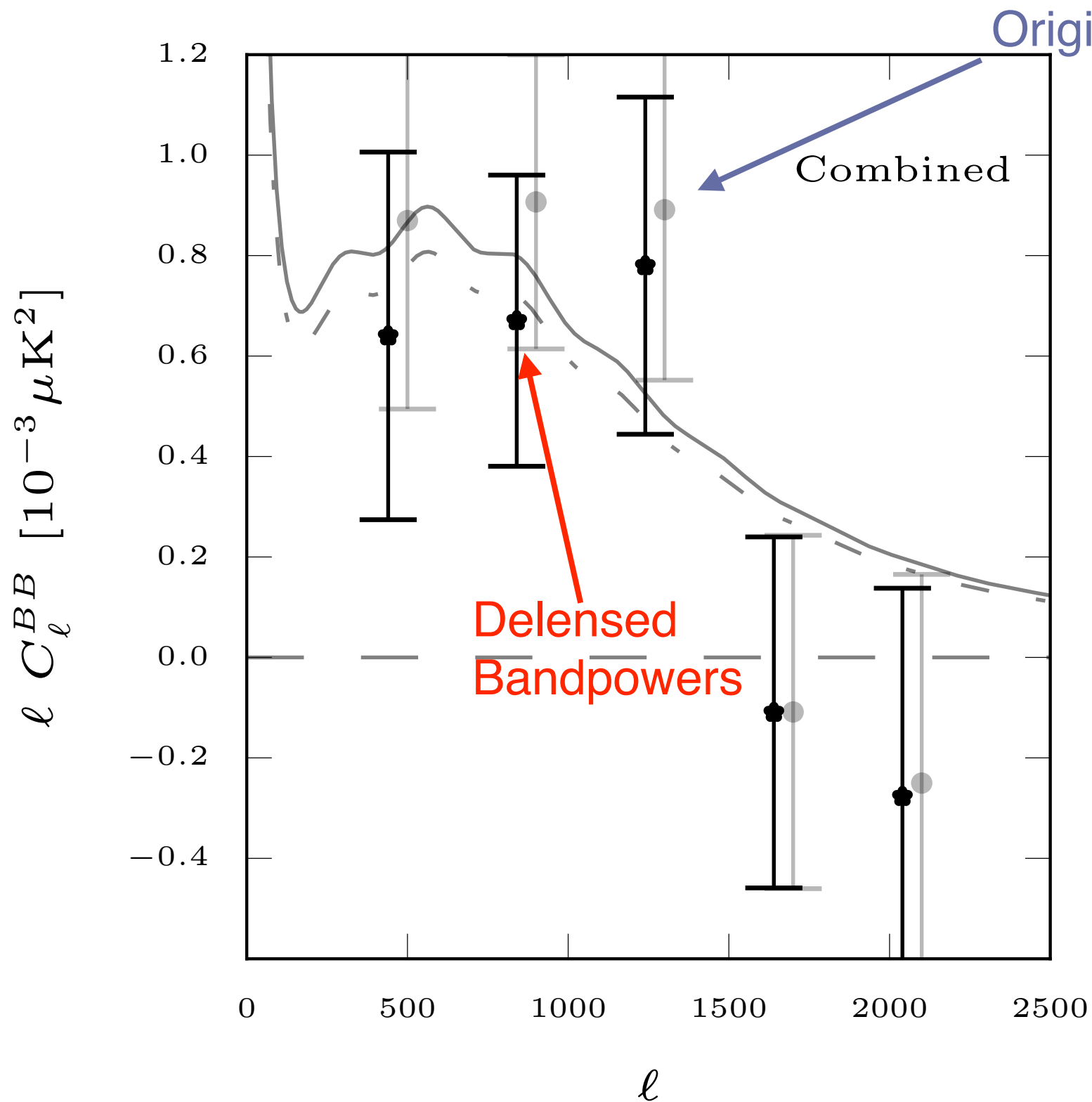


SPT 15-20% DELENSING: THE BAND POWERS



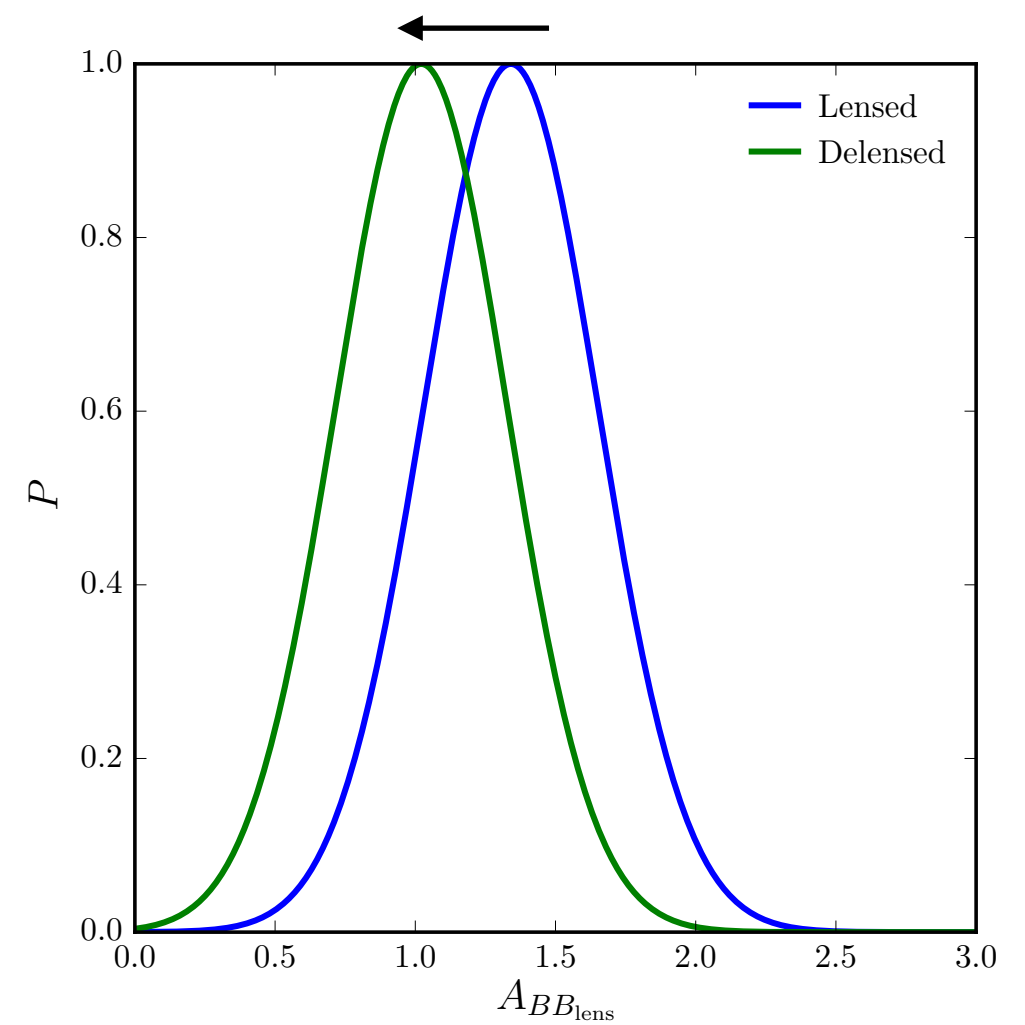
Delens

SPT 15-20% DELENSING: THE BAND POWERS



$$A_{\text{lens}} = 1.34 \pm 0.31$$

$$A_{\text{delens}} = 1.02 \pm 0.30$$



SPT 10% DELENSING: THE SYSTEMATIC TESTS

Run and passed so far

Low-ell cut in E mode: important push as low as possible

High-ell cut in E mode

CIB model assumed

Curl Estimator

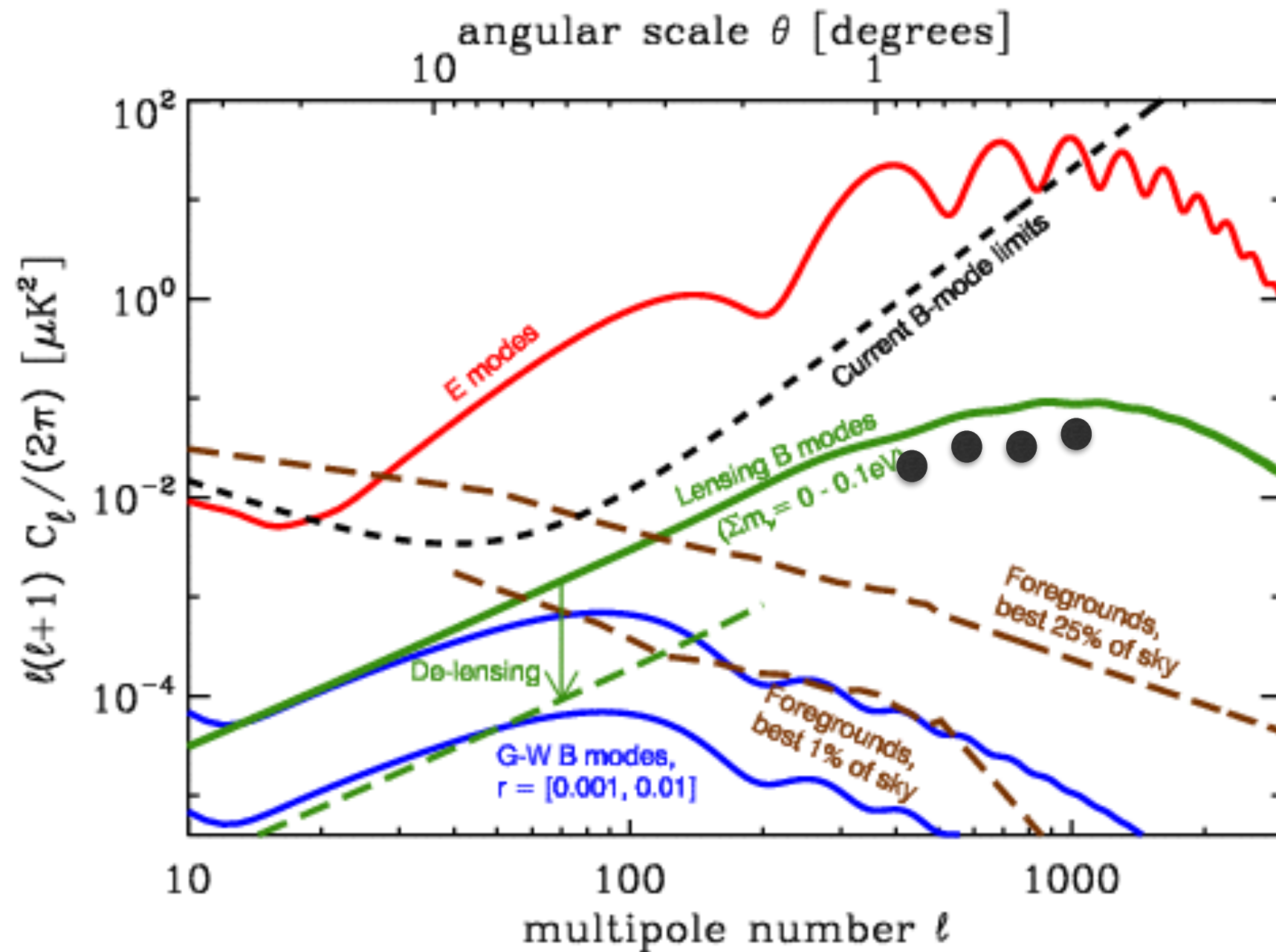
Noise only maps

**AND THE FUTURE WILL BE EVEN BRIGHTER, DELENSING WILL
IMPROVE**

SIMS

Note: we have filtering, foregrounds (gaussian), CIB from model.

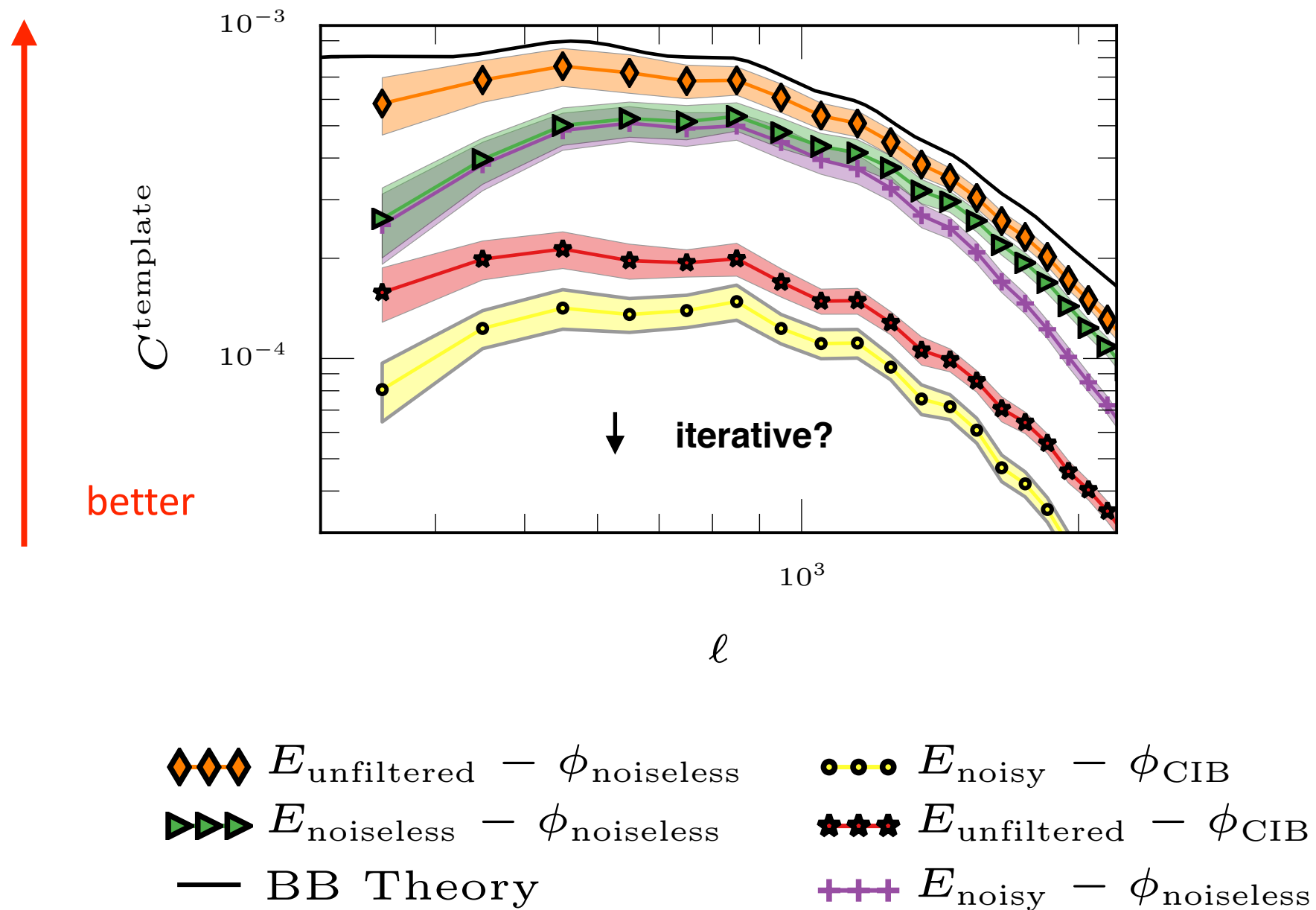
DELENSING: LONG (EXCITING) WAY TO GO.



● This analysis

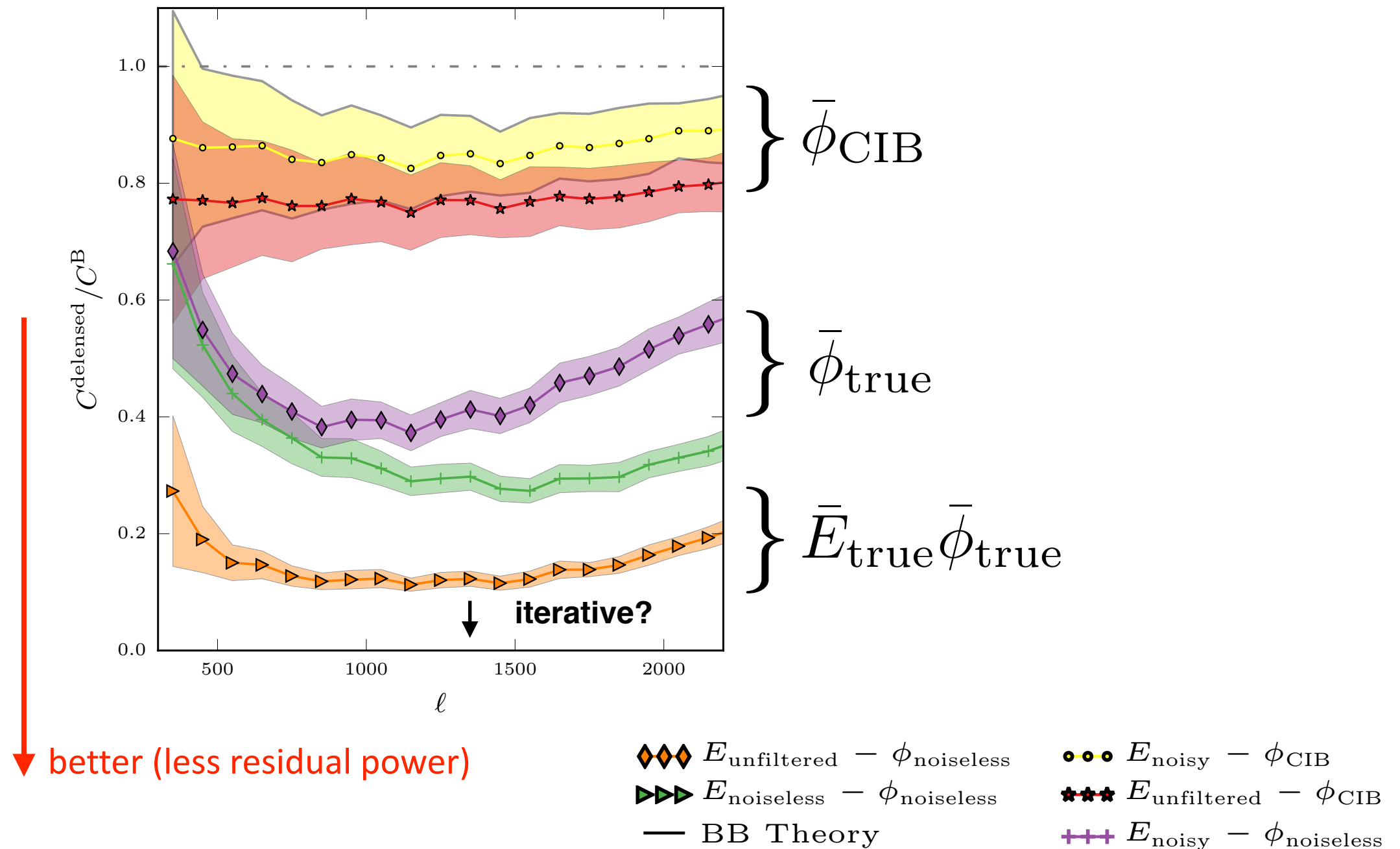
DELENSING EFFICIENCY: BIG PICTURE

B template power spectrum

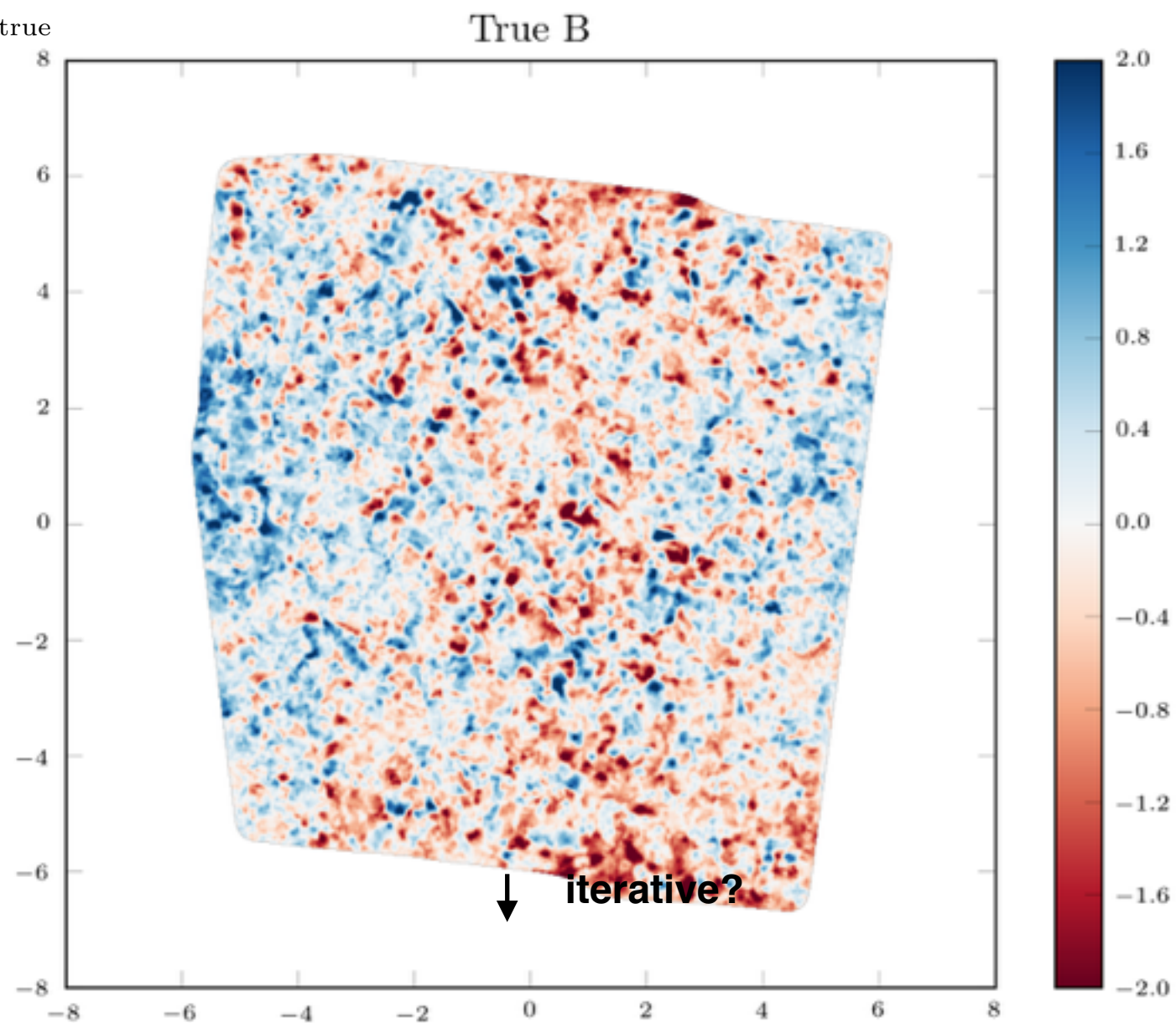
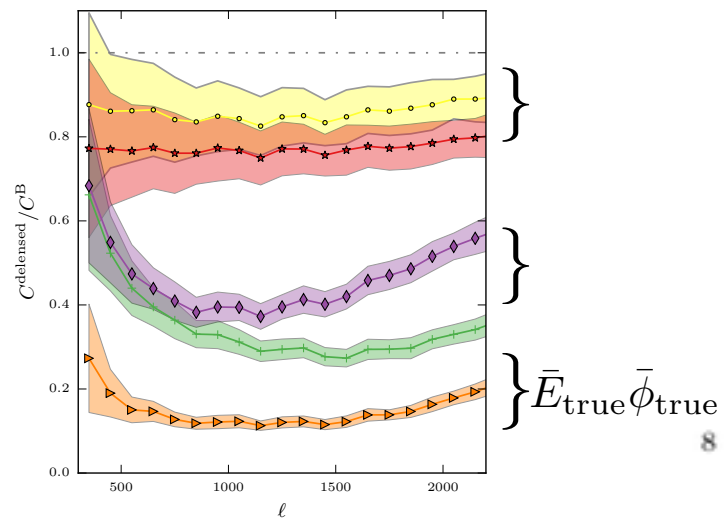


DELENSING EFFICIENCY: BIG PICTURE

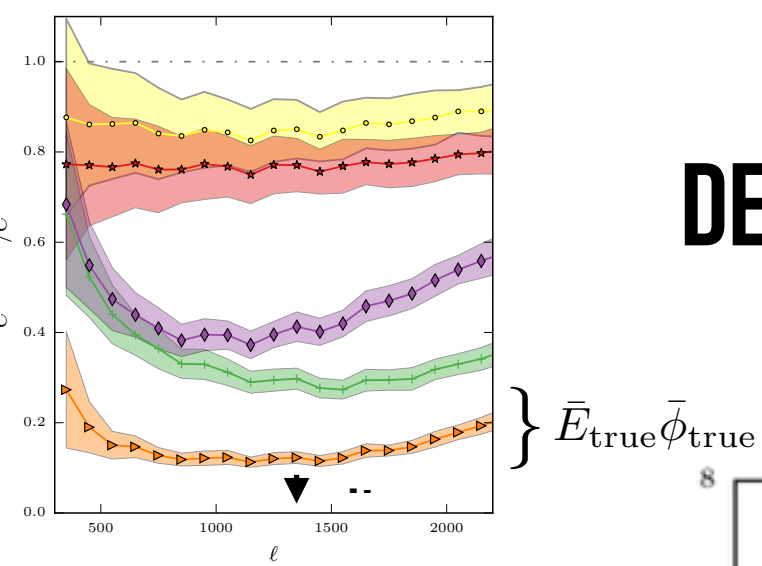
Lensing Clbb residuals



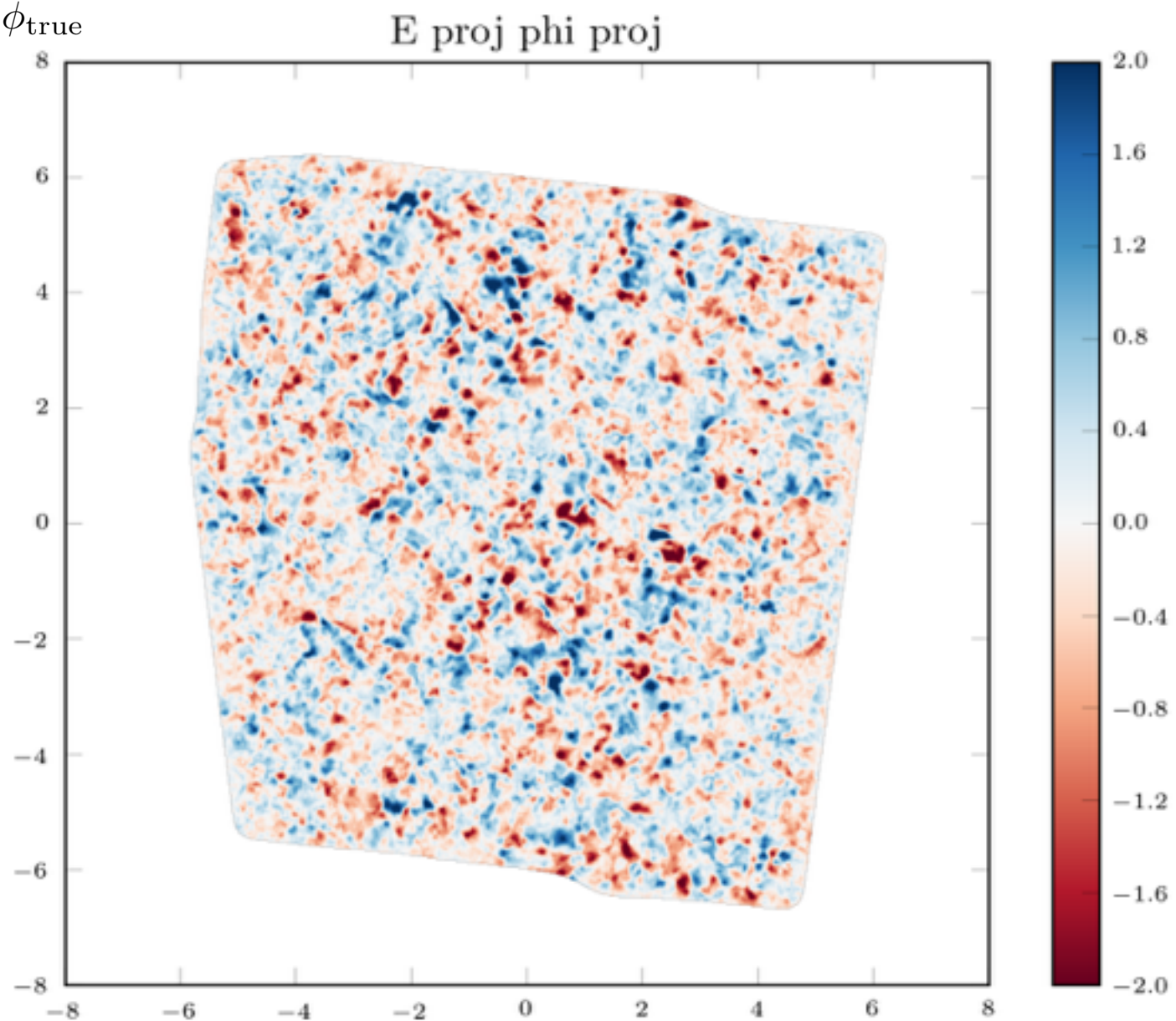
DELENSING EFFICIENCY: MAPS

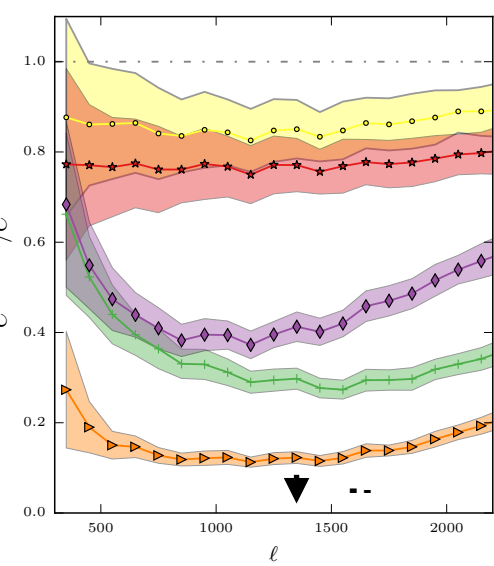


DELENSING EFFICIENCY: PERFECT INPUT



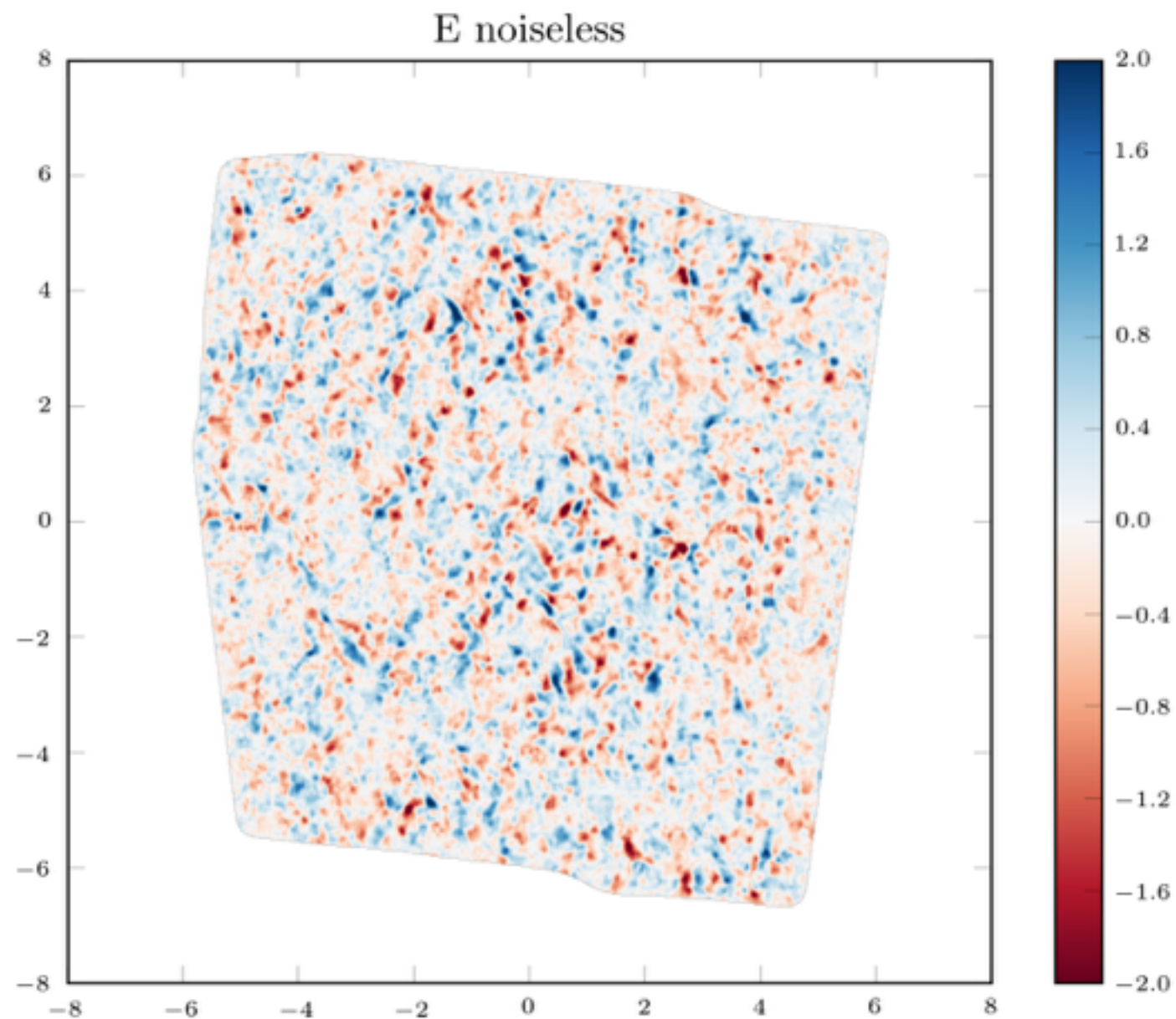
iterative?



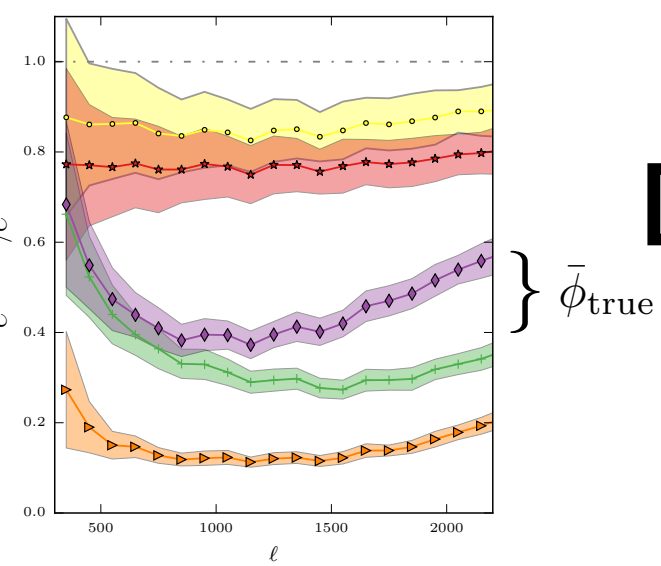


DELENSING EFFICIENCY: NOISELESS FILTERED E

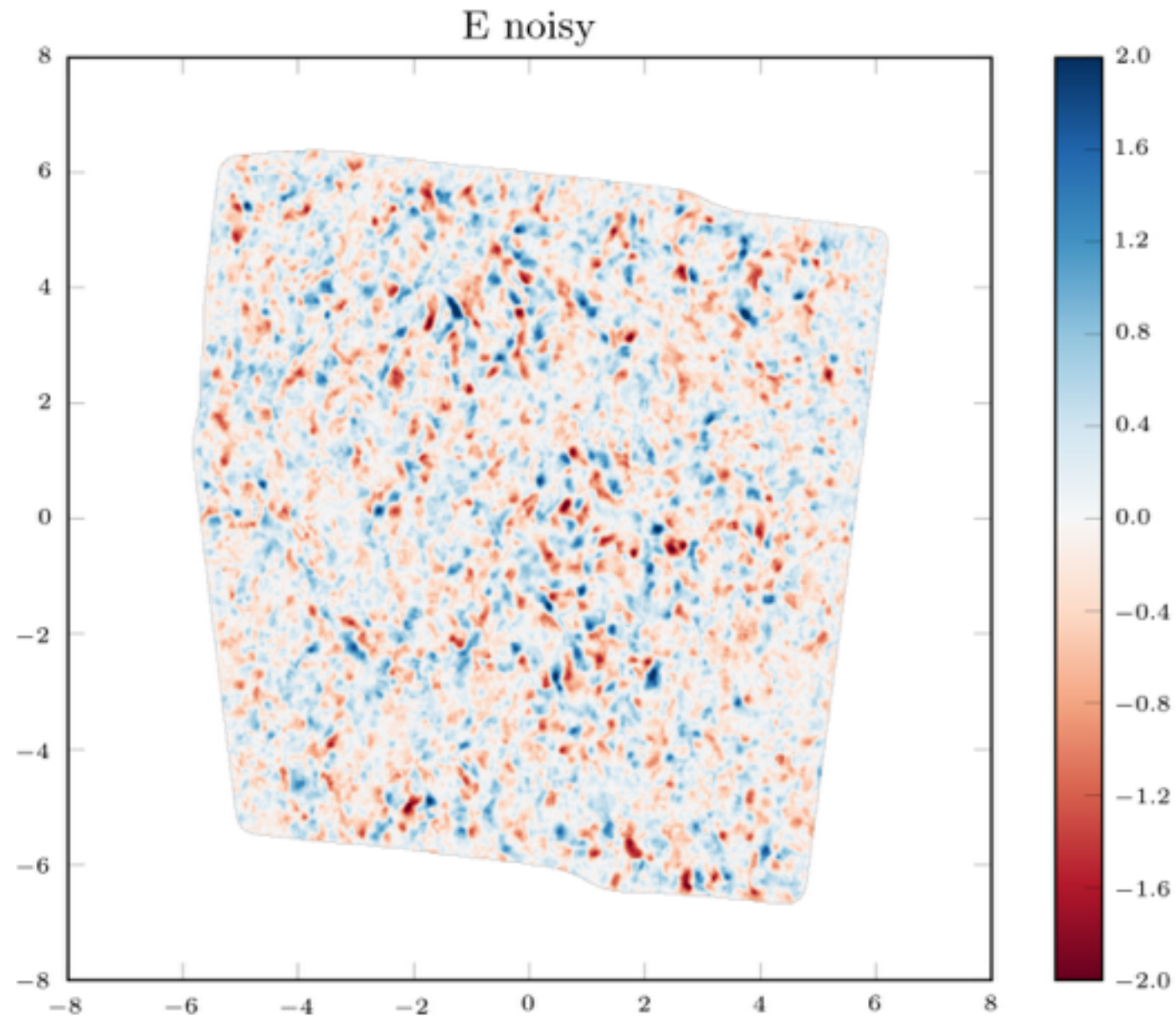
} $\bar{\phi}_{\text{true}}$



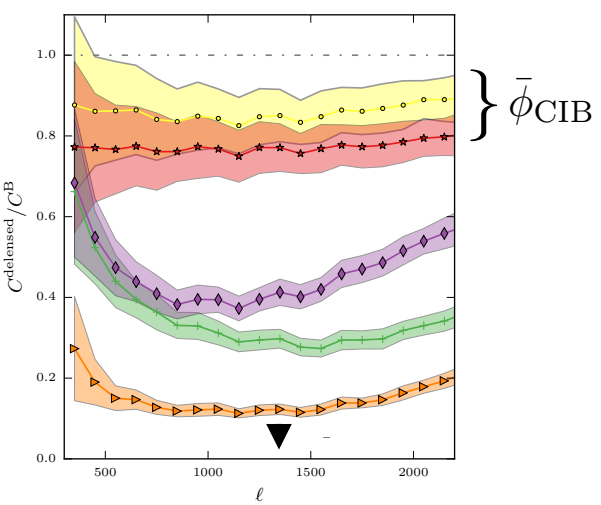
DELENSING EFFICIENCY: NOISY FILTERED E



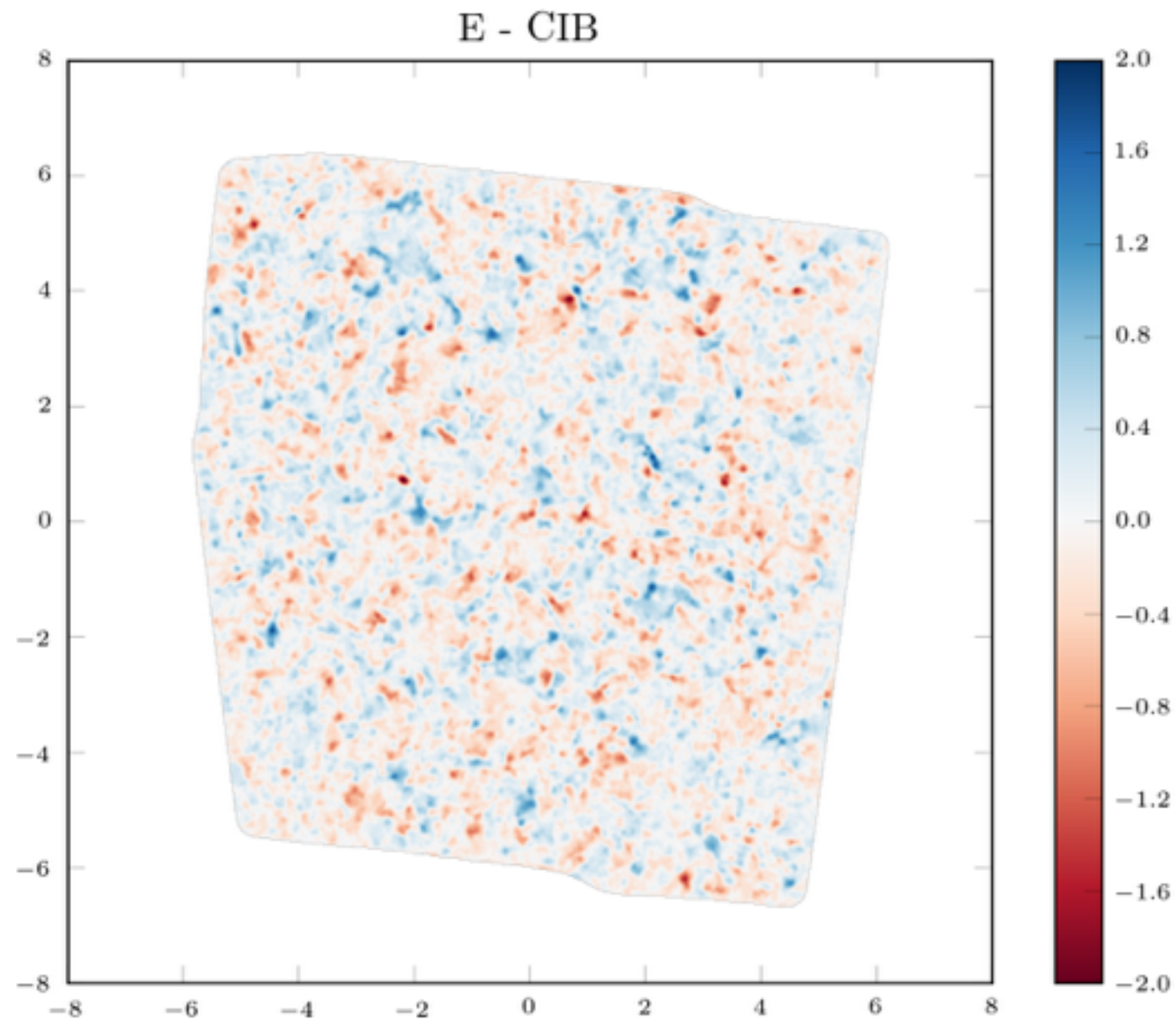
**At least for
SPT at this
scales. E
modes are
not the
problem**



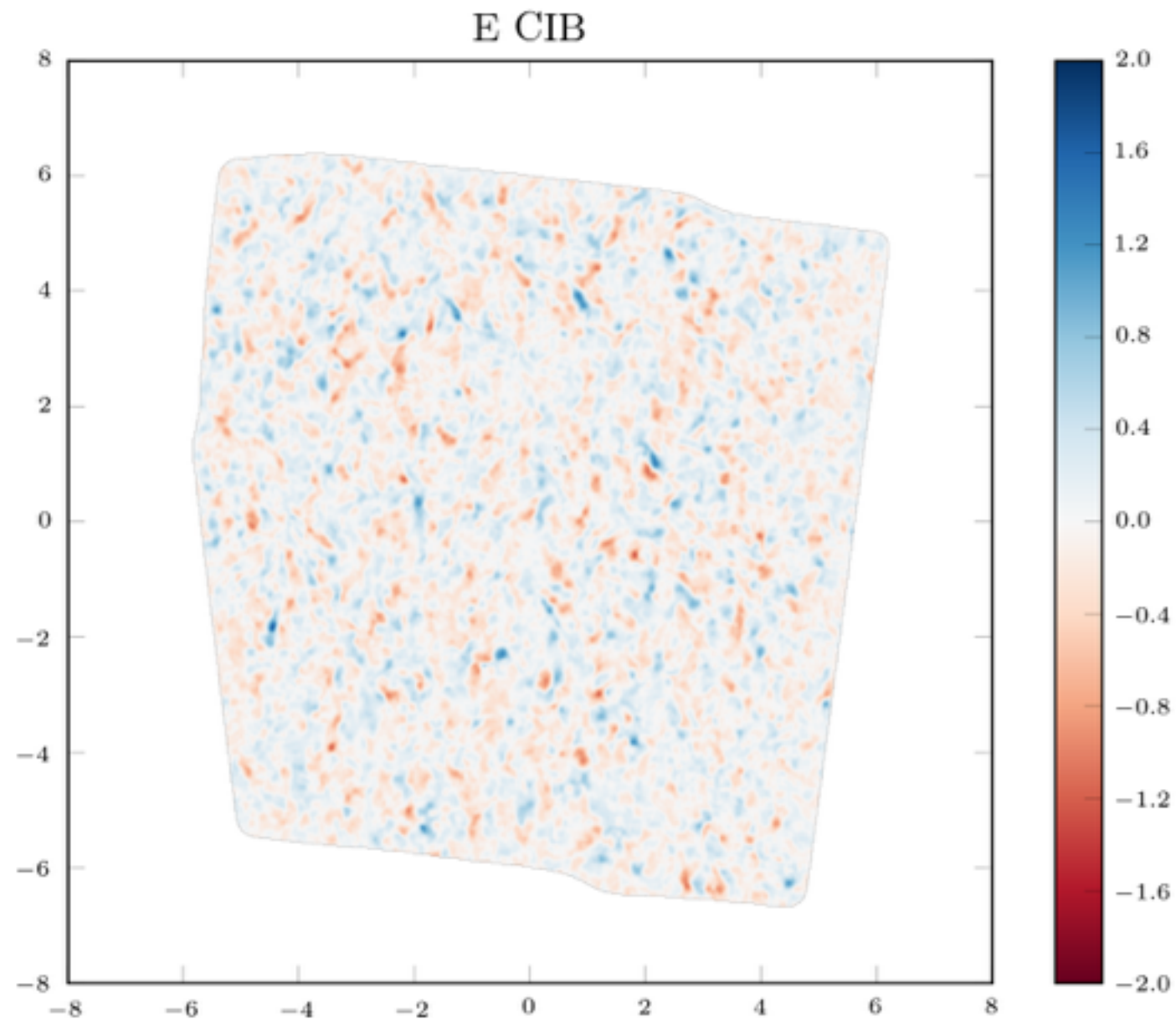
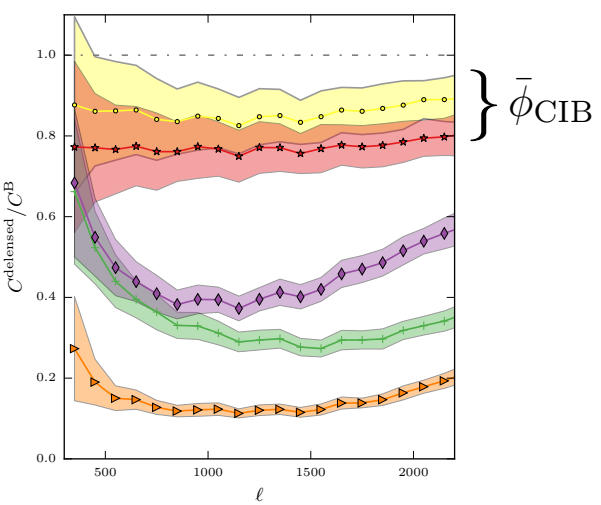
DELENSING EFFICIENCY: MAPS



**Indeed
perfect E but
lensing from
CIB..**



DELENSING EFFICIENCY: MAPS



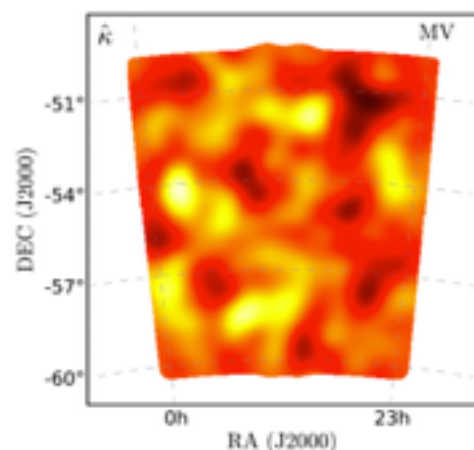
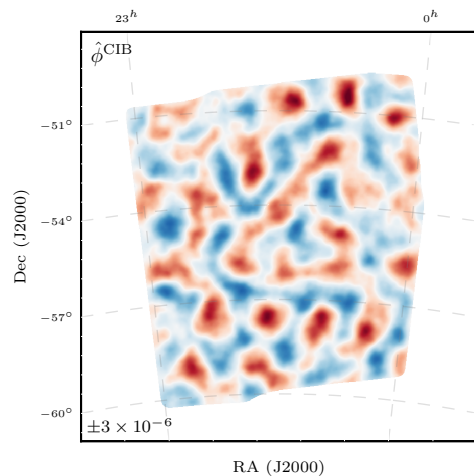
THE CHALLENGES

- The **B mode map** and the **B mode template** we want to subtract are coming from different analysis. They have **different filtering, missing modes, different point sources threshold**.
- We are **testing** the technique for the **first time** on **data**. Using this to improve r constraint **required** an **unprecedented control of systematics**.
- Analyze delensed data. Covariances?
- Estimate systematics contamination: dust.

THE FUTURE

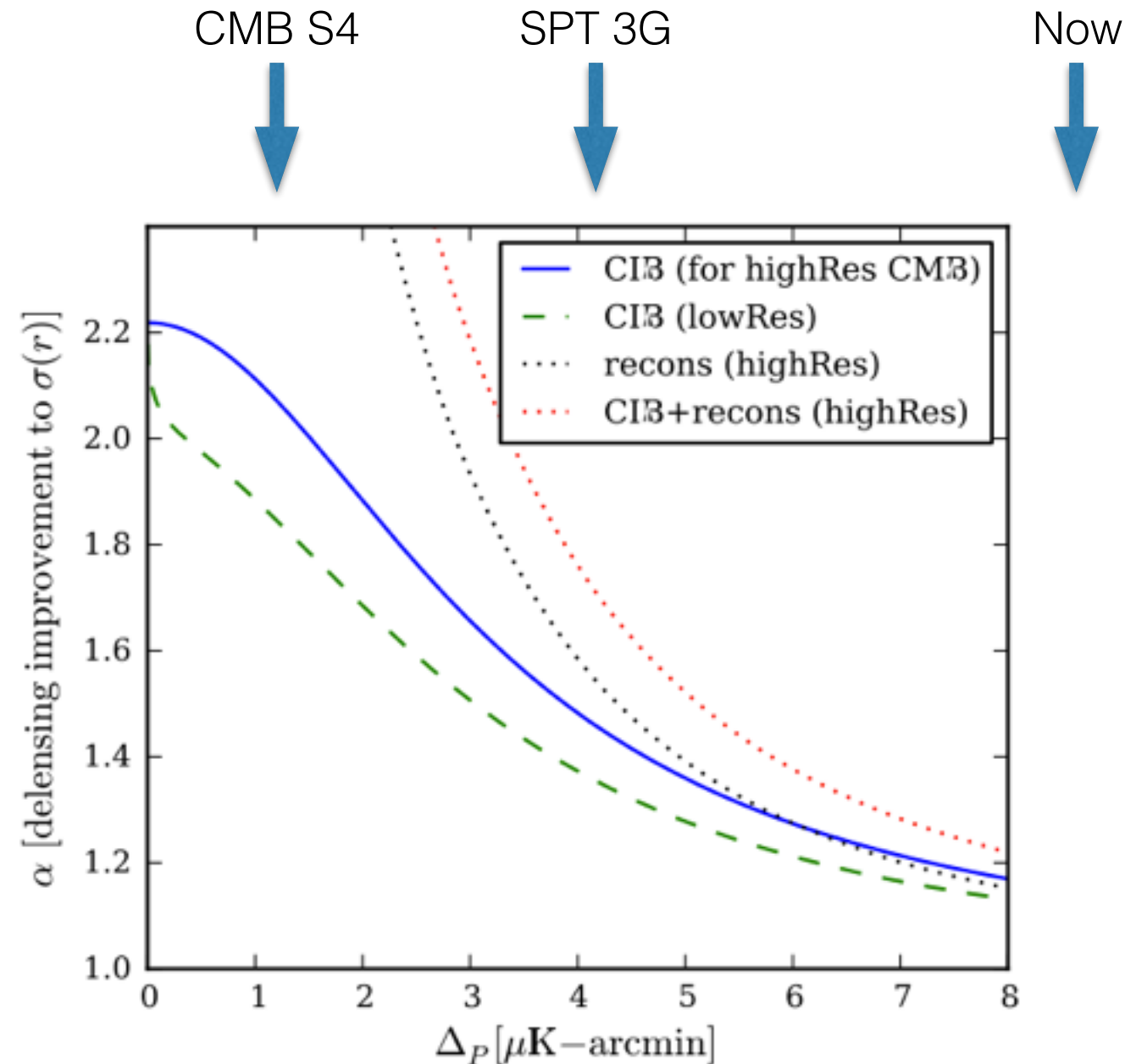
Reasonable goals by end of 2017

- On the 500deg² SPT combine Planck CIB and CMB lensing reconstruction.



- Delens BICEP-KECK with the help of BICEP data.

Lensing Potential from CIB
v.s. CMB reconstruction



Sherwin & Schmittfull 2015

ADVERTISEMENT: 2DX3D FORMALISM IN GALAXY SURVEYS

With Sam Passaglia 1st year



We know how to get cosmology from 2D samples

Expand in $Y_{lm}(\theta)$ Compute $\langle a_{lm} a'_{l'm'} \rangle$

For 3D, we usually expand in e^{ikx} ... but if we want to cross-correlate with 2D:

Expand in $Y_{lm}(\theta)$ AND $j_l(kr)$

Compute $\langle a_{lm} b_{l'm'}(k) \rangle$ and $\langle b_{lm}(k) b_{l'm'}(k') \rangle$

Retains diagonality in l and m

Application: Photo-z Galaxies and Clusters

Photometric surveys produce tomographic galaxy bins

Each bin essentially a 2D sample

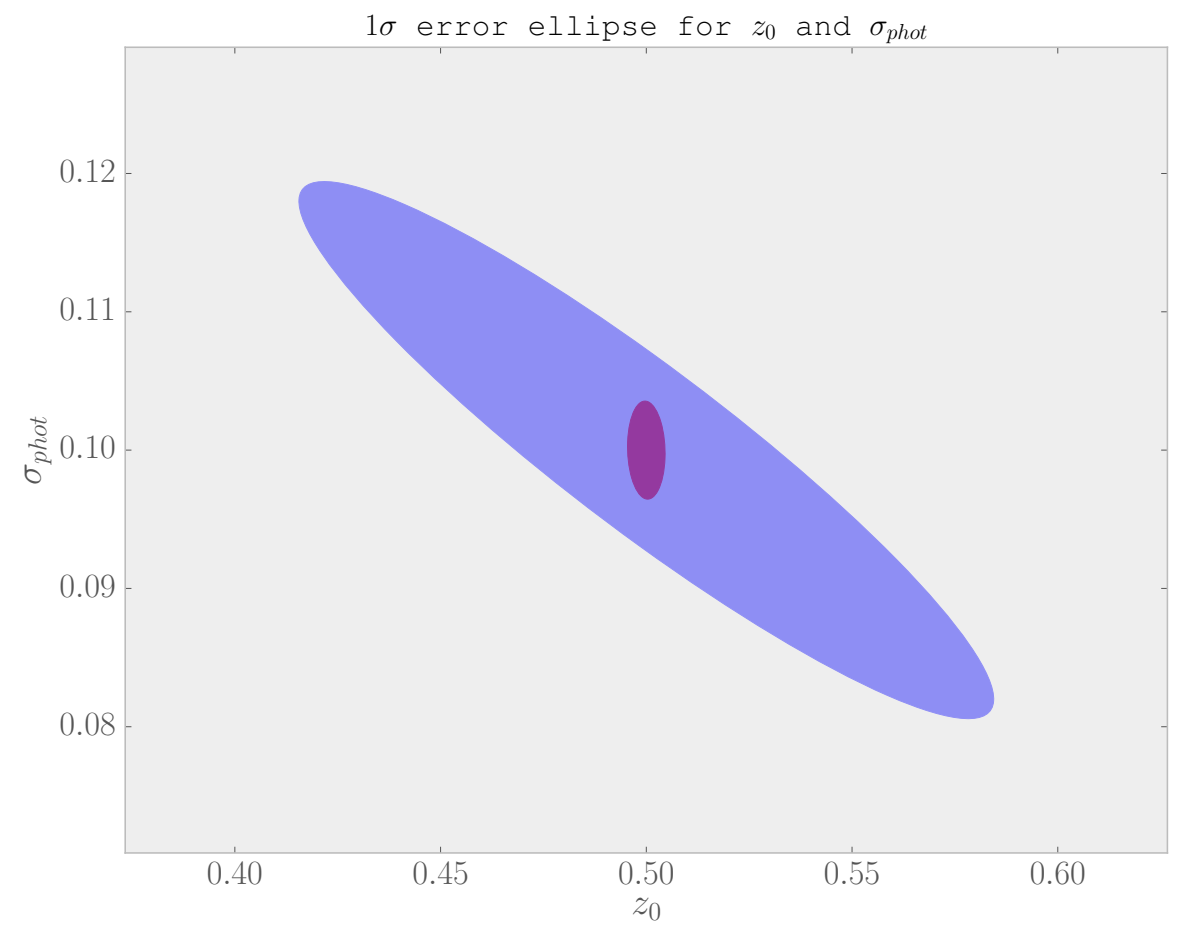
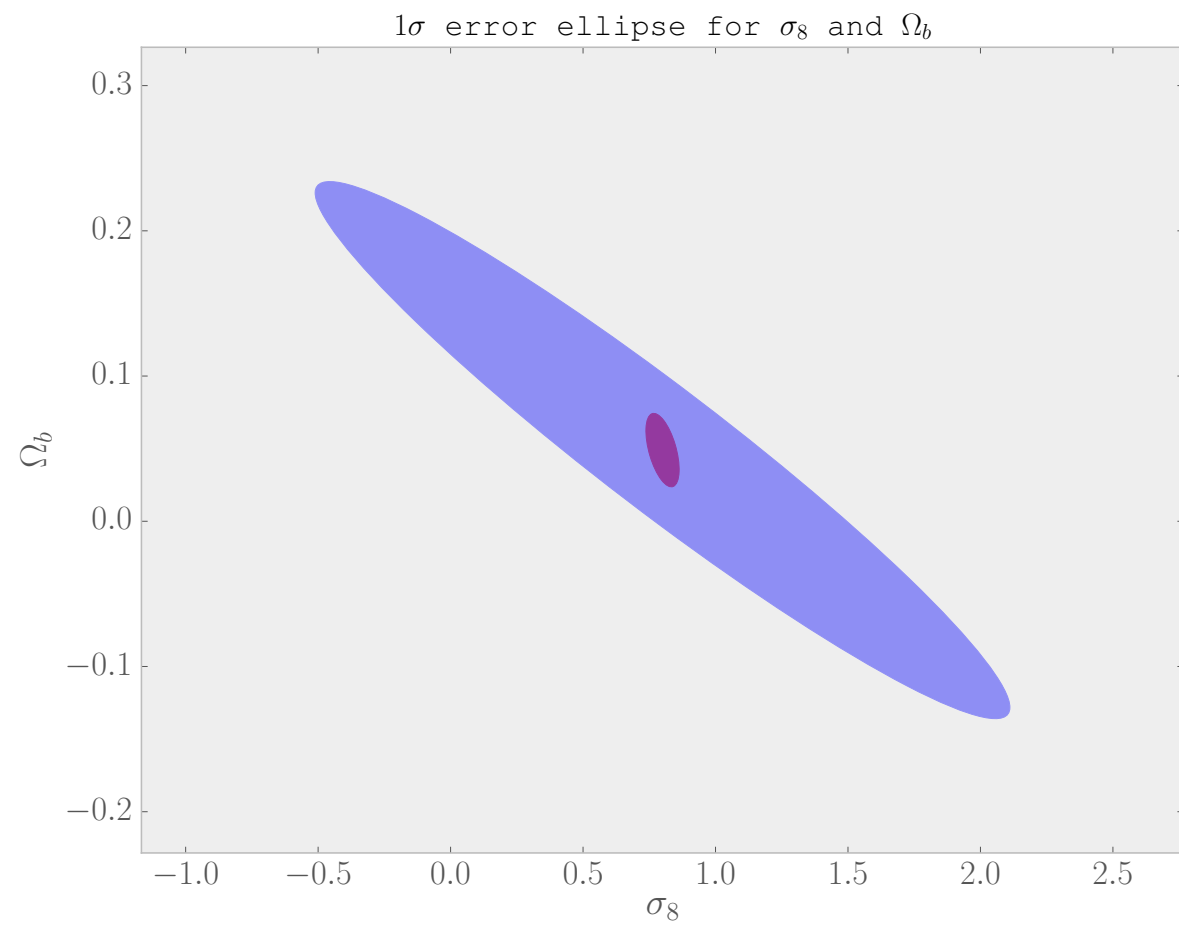
We can use our framework to make optimal use of overlapping 3D samples

Ex: redMapper Clusters, Spectroscopic galaxies

For DES clustering analyses, clusters are lumped with galaxies

What if we treat clusters as a true 3D sample?

Results: Fisher Analysis for a DES-like survey



CONCLUSION

- Delensing is crucial and it is working. Results in agreement with sims. Right now all the collaborations and the CMB Stage 4 community are working hard.
- Happy to chat about:
 - 2Dx3D formalism
 - dark matter perturbation theory
 - LIGO early localization of electromagnetic counterparts,
 - modular software for parameters constraints,
 - CMB Stage 4 and galaxies forecast,
 - optimal map reconstruction: ISW
 - effect of long wave modes on deep CMB experiments.

Alessandro Manzotti, KICP Chicago